Blueprints
Setting up an HPC cluster with Red Hat Enterprise Linux
Blueprints

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Chapter 1. Scope, requirements, and support

This blueprint applies to PowerLinux™ (POWER6® and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.

Systems to which this information applies

PowerLinux (POWER6 and later)

Intended audience

This blueprint is intended for advanced Linux system administrators and programmers who are already familiar with basic HPC concepts, terminology, products, including InfiniBand® interconnects. The instructions assume that you have a general understanding of the usage requirements for connecting nodes with InfiniBand and with MPI-based applications.

Scope and purpose

This document is based in part on the collaborative experiences of the IBM® Linux Technology Center, IBM's systems development teams, and Rice University in deploying and managing the POWER7-based BlueBioU cluster, at [http://bluebiou.rice.edu/](http://bluebiou.rice.edu/).

This document discusses the following software that you can use to deploy a simple cluster with POWER-based systems:

- Basic InfiniBand setup
- Open MPI
- Torque
- IBM Advance Toolchain for PowerLinux
- libhugetlbfs

The following topics are not covered:

- Advanced cluster management products, such as:
  - Moab (Cluster Resources)
  - IBM Parallel Environment
  - Extreme Cloud Administration Toolkit (xCAT)
- Detailed problem determination
- In-depth technology discussion

Resources for in-depth discussion of the these and other topics are listed in Related Information

Test environment

The instructions in this blueprint were tested on IBM Power® 575 systems with POWER6 processors running Red Hat Enterprise Linux 5.5. The BlueBioU team at Rice University has deployed a similar software stack with POWER7-based IBM Power 750 systems.
Hardware, software, and other prerequisites

In testing, one server was used as a “management node” and two other servers were the “compute nodes”. Each server had an InfiniBand adapter supporting physical connections to a shared InfiniBand switch.

The examples in this demonstration are focused on eHCA with a single port.

The following software resources are used to perform the steps in this blueprint:

- A Red Hat Enterprise Linux 5.5 YUM repository
- Torque Resource Manager software from [http://www.clusterresources.com/torquedocs21/1.1installation.shtml](http://www.clusterresources.com/torquedocs21/1.1installation.shtml)

This blueprint focuses on Red Hat Enterprise Linux 5.5, but you can apply the concepts easily to other Linux distributions that are supported on POWER-based systems.

The Red Hat createrepo RPM package must be installed on all nodes of the cluster.

The Red Hat Enterprise Linux 5.5 YUM repository must be available on each of the nodes.

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IBM Services

Linux offers flexibility, options, and competitive total cost of ownership with a world class enterprise operating system. Community innovation integrates leading-edge technologies and best practices into Linux.

IBM is a leader in the Linux community with over 600 developers in the IBM Linux Technology Center working on over 100 open source projects in the community. IBM supports Linux on all IBM servers, storage, and middleware, offering the broadest flexibility to match your business needs.

For more information about IBM and Linux, go to [ibm.com/linux](https://www.ibm.com/linux)

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You can also find additional information in the following forums:

Chapter 2. Open source-based HPC compute cluster on POWER

You can learn about basic concepts of HPC clusters, and get a brief overview of some of the open source software you can use to build an HPC cluster on POWER processor-based systems.

HPC compute clusters

This blueprint is focused on the class of servers which are used primarily for compute-intensive work like computational simulations of weather, bioinformatics, and so on. In this class of compute-intensive workloads, a single compute job may execute on multiple servers simultaneously and often requires extensive communication between each of the servers. In these server clusters, the servers typically share a dedicated high-speed network (often based on InfiniBand), are densely and closely located relative to each other, and are homogeneous.

Management node

A management node, typically a separate server, is used for running the cluster's scheduler and resource managers. This blueprint shows how to install a Maui Cluster Scheduler and the Torque Resource Manager which collectively manage and control the compute nodes.

Compute node

With a large number of compute nodes, there is usually a requirement for schedulers and server resource managers to prioritize and manage which jobs can be executed on the cluster. In this blueprint, we focus on just a handful of compute nodes, with the notion that the compute node setup is a repeatable incremental process. As you need to increase the number of compute nodes in your cluster, you can refer to these examples to ensure that the additional nodes are properly prepared.

InfiniBand interconnect

The example cluster in this blueprint uses InfiniBand to connect the nodes of the cluster. InfiniBand is a scalable, low-latency, high performance communication mechanism frequently used in HPC environments.

The software components

These are the essential components of the HPC software stack, including compilers, math libraries, communication stack, cluster management and scheduling software, and software used for installation of key software components for POWER processor-based systems.

IBM Installation Toolkit for PowerLinux

The IBM Installation Toolkit for PowerLinux provides a set of tools that simplifies the installation of IBM value-added software necessary to fully use the capabilities of the Power platform. In particular, for this cluster we are interested in the two 64-bit Open MPI packages included in the IBM Installation Toolkit Version 4.1.
**InfiniBand software stack**

The InfiniBand software stack provides cluster-knowledgeable middleware, such as MPI libraries, access to the low-latency, high bandwidth InfiniBand fabric for cluster communications. Red Hat Enterprise Linux provides an InfiniBand software stack.

**Open MPI**

The Open MPI project provides an open source implementation of the MPI-2 standard. It is developed and maintained by a consortium of academic, research, and industry partners. Open MPI is therefore able to combine the expertise, technologies, and resources from across the High Performance Computing community in order to build reliable and high performance MPI library.

**IBM Advance Toolchain for PowerLinux**

The IBM Advance Toolchain for PowerLinux is a collection of free software application development products specifically tailored to make use of IBM POWER processor features. The package includes GCC (GNU Compiler Collection), GLIBC (GNU C Libraries), GNU binary utilities, GDB (GNU debugger), and the performance analysis tools (QProfile and Valgrind) in a self contained Toolchain. The IBM Advance Toolchain for PowerLinux duplicates the function of packages already delivered by Linux distributors but provides additional features for the POWER6 and POWER7® processors as indicated in the IBM Advance Toolchain for PowerLinux Release Notes® 'Features' section. The IBM Advance Toolchain for PowerLinux is built and distributed by the University of Illinois.

**TORQUE resource manager**

Tera-scale Open-source Resource and QUEue Manager (TORQUE) is a workload and resource-management system that manages batch jobs and compute nodes and schedules the execution of those jobs. The TORQUE system includes three pieces: the server, the scheduler, and the job executor. The server process, called pbs_server, creates and manages jobs and queues and dispatches jobs for execution to compute nodes, where the job executor, called pbs_mom, starts the job.

**Maui Cluster Scheduler**

The Maui Cluster Scheduler is a policy engine used to improve the manageability and efficiency of various sized clusters, from small clusters with just a few processors to very large supercomputers. The Maui Cluster Scheduler is intended to support a large array of scheduling policies, dynamic priorities, extensive reservations, and fairshare.

**IBM XL C/C++ and XL Fortran compilers**

XL C/C++ for Linux V11.1 is a highly advanced optimizing compiler for the selected Linux distributions. The compiler runs on IBM Power Systems™ and is an industry standards-based professional programming tool that can be used for developing large, complex, computationally intensive 32-bit and 64-bit applications in the C and C++ programming languages.

XL Fortran is a standards-based Fortran compiler with extensive features to help you create high performance applications. A highly advanced optimizing compiler for the Linux operating system, runs on IBM Power Systems.

**libhugetlbfs**

The libhugetlbfs library interacts with the Linux hugetlbfs to make large pages available to applications in a transparent manner. On POWER processor-based systems, this library provides applications easy access to the 16 MB huge pages.
ATLAS math libraries

Automatically Tuned Linear Algebra Software (ATLAS) provides highly optimized Linear Algebra kernels for arbitrary cache-based architectures. ATLAS provides ANSI C and Fortran77 interfaces for the entire BLAS API, and a small portion of the LAPACK AP.

Related concepts:
Chapter 1, “Scope, requirements, and support,” on page 1

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.
Chapter 3. Setting up the cluster

You can see an overview of the cluster component setup for this example, including whether components are set up on the management node or compute nodes, and which user does the installation or configuration tasks.

The cluster is dependent on each of the compute nodes being connected with InfiniBand. Although it is common that all nodes have an InfiniBand connection, it is not required for the management node. However, the InfiniBand packages should still be installed on the management node so that other package builds can use the InfiniBand components. Therefore, we start by installing the latest Open MPI and InfiniBand packages on all nodes - the management node and all compute nodes.

The installation and configuration tasks are performed by the root user except where noted in the following tables.

Table 1. Cluster setup tasks

<table>
<thead>
<tr>
<th>Task</th>
<th>Management node</th>
<th>Compute node</th>
</tr>
</thead>
<tbody>
<tr>
<td>Installing OpenMPI and InfiniBand packages</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>Configuring InfiniBand</td>
<td>Not required</td>
<td>Yes</td>
</tr>
<tr>
<td>Installing Torque Resource Manager</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>Installing Maui Cluster Scheduler</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>Configuring Torque</td>
<td>Yes</td>
<td>Yes</td>
</tr>
</tbody>
</table>

Table 2. Advanced software setup tasks

<table>
<thead>
<tr>
<th>Task</th>
<th>Management node</th>
<th>Compute node</th>
</tr>
</thead>
<tbody>
<tr>
<td>Installing libhugetlbfs</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>Installing IBM Advance Toolchain for PowerLinux</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>Installing the IBM XL C/C++ and Fortran compilers</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>Installing ATLAS math libraries</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>Building Open MPI with Torque</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>Configuring Open MPI for use with the Advance Toolchain</td>
<td>Yes, as hpc user</td>
<td>Yes, as hpc user</td>
</tr>
<tr>
<td>Configuring Open MPI for use with the IBM XL compilers</td>
<td>Yes, as root when installing and then as hpc user when verifying</td>
<td>Yes, as root when installing and then as hpc user when verifying</td>
</tr>
<tr>
<td>Using Open MPI with huge pages</td>
<td>Yes, as hpc user</td>
<td>Yes, as hpc user</td>
</tr>
<tr>
<td>Testing the InfiniBand interconnect performance with Intel MPI Benchmark (IMB)</td>
<td>Yes, as hpc user when installing and submitting jobs</td>
<td>Yes, as hpc user when installing</td>
</tr>
</tbody>
</table>
Setting up the hpc user

The hpc user configures and uses various optional software components on the cluster, including Open MPI, the IBM XL compilers, and the Intel MPI Benchmark (IMB).

About this task

You must ensure that the hpc user exists on all the nodes of the cluster in order to perform some of the configuration and testing tasks described in this blueprint.

The hpc user needs password-less connectivity among all the nodes in order to enable Open MPI applications to pass messages between nodes. Without password-less connectivity, you would be required to enter the password for each node whenever a job was run. The stage needs to be set just so.

Procedure

1. Create the hpc user on any nodes where it does not already exist. If the hpc user does not exist on a node, you can create the hpc user with the following commands:
   
   ```
   # useradd -m hpc
   # passwd hpc
   ```

2. Set up password-less connectivity for the hpc user among all the nodes in the cluster:
   
   On the management node and all compute nodes, check if hpc user has password-less connectivity. You must be able to use ssh to connect to and from all the nodes without a password request. (There are several methods available to set up password-less connectivity, outside the scope of this document.)

   When you have successfully configured ssh for the hpc user, you will be able to use ssh to connect between any two nodes in the cluster without a password. The following example shows a password-less ssh connection from the host named compute_node1 to the host named compute_node2:

   ```
   [compute_node1] # su – hpc
   [compute_node1] $ ssh compute_node2
   Warning: Permanently added 'compute_node2' (RSA) to the list of known hosts.
   [compute_node2] $
   ```

Installing Open MPI and InfiniBand packages

You can obtain and use the IBM Installation Toolkit for PowerLinux to install the Open MPI and InfiniBand software packages.

Before you begin

1. Ensure that the createrepo RPM package is installed on each node of the cluster.

**Note:**
- You must register and sign in before you can download the software.
- As of the time of writing of this blueprint, the current IBM Installation Toolkit version is 4.1.

**About this task**

In these examples we assume the operating system (Red Hat Enterprise Linux 5.5) has already been installed on all of the servers – in this case the management node and the two compute nodes.

**Note:** The IBM Installation Toolkit can be used to install the Linux distribution for servers as well, but installing the operating system is outside the scope of this discussion.

The root user performs all the steps of this procedure.

Perform these steps for each node of the cluster:

**Procedure**

1. Create a local IBM Installation Toolkit YUM repository:
   a. Mount the IBM Installation Toolkit ISO media and copy the Red Hat directory with all of the Red Hat-related RPM packages to a directory of your choice. The following example uses /opt/ibmit41 as the destination directory:

   ```bash
   # mkdir /mnt/ibmtoolkit
   # mkdir /opt/ibmit41
   # mount -o loop -t iso9660 IBM_Installation_Toolkit_41.iso /mnt/ibmtoolkit
   # cp -arL /mnt/ibmtoolkit/* /opt/ibmit41
   # umount /mnt/ibmtoolkit
   # rmdir /mnt/ibmtoolkit
   
   **Note:** This example, uses the `cp` command’s `-L` flag order to dereference and copy files that are symbolic links in the `/RedHat` directory on the IBM Installation Toolkit ISO image.
   
   b. Use the `createrepo` command to create the repository, as in the following example:

   ```bash
   # createrepo /opt/ibmit41/RedHat
   33/33 - RPMS/xconfig-0.1-1.ppc.rpm
   Saving Primary metadata
   Saving file lists metadata
   Saving other metadata
   
   c. Create the definition file for this new repository.

   The `/etc/yum.repos.d` directory is the default YUM repository location. Therefore, in this example, the definition file is created as `/etc/yum.repos.d/ibmit41.repo`. The content of the definition file should look like the following example.

   **Note:** The `baseurl` parameter is set to point to the local directory where the `createrepo` command was issued against in the previous step and where the Red Hat RPM packages reside.

   ```ini
   [ibmit41]
   name=ibmit41
   baseurl=file:///opt/ibmit41/RedHat
   enabled=1
   gpgcheck=0
   
   d. Verify that the local repository is set up correctly, as in the following example:

   ```bash
   # yum repolist
   Loaded plugins: rhnplugin, security
   This system is not registered with RHN.
   RHN support will be disabled.
2. Install the Open MPI and InfiniBand-related packages from the local IBM Installation Toolkit YUM repository and the Red Hat Enterprise Linux 5.5 YUM repository.

```bash
# yum install sysstat \
openmpi-1.4.2-1.ppc64 \
openib mpi-selector infiniband-diags perf test ofed-docs \
libibverbs* librdmacm* libehca*
```

**Note:**
- "sysstat" is a package for extended performance tools on a Power system.
- The Open MPI package is provided on the IBM Installation Toolkit. This is a newer package of Open MPI built for 64-bit applications which has been packaged and provided for customers.
- The remainder of the packages are standard packages necessary for MPI applications using InfiniBand connectivity.
- "ofed" is from the OpenFabrics Alliance – [https://www.openfabrics.org/index.php](https://www.openfabrics.org/index.php) The OpenFabrics Enterprise Distribution (OFED) is a standardized set of enabling software generally targeted at high-performance low-latency computing.

3. Configure the PATH and LD_LIBRARY_PATH environment variables for the hpc user to include the paths for Open MPI and software installed in `/usr/local/sbin` for this HPC cluster configuration by modifying the `/home/hpc/.bashrc` file as follows:

   a. Add the `/usr/local/sbin` directory and the `/opt/openmpi/1.4.2/bin` directory to the beginning of the PATH environment variable.

   b. Add the `/opt/openmpi/1.4.2/lib` directory to the beginning of the LD_LIBRARY_PATH environment variable.

The following example shows a simple method to append these modifications to the environment variables in the `.bashrc` file for the hpc user:

```bash
cat >> /home/hpc/.bashrc <<EOF
export PATH=/usr/local/sbin:/opt/openmpi/1.4.2/bin:$PATH
export LD_LIBRARY_PATH=/opt/openmpi/1.4.2/lib:$LD_LIBRARY_PATH
EOF
```

**Results**

After you have completed this installation process on each node of the cluster, every system will have the required Open MPI and InfiniBand software installed.

**What to do next**

You are now ready to configure and validate the InfiniBand connectivity between all the InfiniBand-connected nodes.

**Related concepts:**

[Chapter 1, “Scope, requirements, and support,” on page 1](#)

This blueprint applies to PowerLinux (POWER5 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.

**Configuring InfiniBand**

You can learn about the steps needed to configure and confirm InfiniBand connectivity.
Before you begin

The Open MPI and InfiniBand packages must already be installed on all nodes.

The allowable amount of locked (pinned) memory needs to be set to unlimited. To do this, edit /etc/security/limits.conf and add the following lines:

```
#<domain>  <type>  <item>  <value>
#
*    soft  memlock  unlimited
*    hard  memlock  unlimited
```

About this task

These steps assume your servers have InfiniBand adapters installed and are connected to an InfiniBand switch. In this example, all nodes are assumed to be connected to the same InfiniBand fabric.

This procedure is required for all nodes that will have InfiniBand traffic.

Note: You will only perform this process on the management node if the management node has an InfiniBand connection. The root user performs all the steps of this procedure.

Procedure

1. Specify the `nr_ports` and `port_act_time` options for the IBM InfiniBand eHCA kernel module, `ib_ehca`, by creating the `/etc/modprobe.d/ib_ehca.conf` file containing the following line:

   ```
   options ib_ehca nr_ports=-1 port_act_time=120
   ```

   Note:
   - The `nr_ports` option is set to -1. This causes the module to autodetect the number of active ports.
   - `port_act_time` option is set to 120. This causes the module to wait for 120 seconds for port activation.

2. Edit `/etc/ofed/openib.conf` and change the values of `SDP_LOAD`, `RDS_LOAD`, `SRP_LOAD`, and `ISER_LOAD` to no. This changes the default setting to load only the drivers that are needed for this setup. The resulting file will be similar to the following example:

   ```
   # Load IPoIB
   IPOIB_LOAD=yes
   # Load SDP module
   SDP_LOAD=no
   # Load the RDS protocol driver
   RDS_LOAD=no
   # Load SRP module
   SRP_LOAD=no
   # Load iSER module
   ISER_LOAD=no
   # Should we modify the system mtrr registers? We may need to do this if you get messages from the ib_ipath driver saying that it couldn't enable
   # write combining for the PIO buffs on the card.
   FIXUP_MTRR_REGS=no
   ```

3. Configure the openibd service:
   a. Run `chkconfig` to configure the openibd service to start automatically whenever the operating system starts, as shown in the following example:

      ```
      # chkconfig openibd on
      # chkconfig --list openibd
      openibd  0:off  1:off  2:on  3:on  4:off  5:off  6:off
      ```

      Note: The output from `chkconfig --list openibd` in this example shows whether the openibd service will start for each runlevel.

   b. Run the `kudzu` command to detect the InfiniBand hardware.
Note: The /etc/sysconfig/hwconf file will also be created which is referenced by the openibd service.

c. Start the openibd service as shown in the following example:

```
# service openibd start
Loading OpenIB kernel modules: [ OK ]
```

4. Validate InfiniBand device configuration by displaying InfiniBand devices on the node:

a. To list InfiniBand devices on the node, run the `ibv_devices` command. This step validates that the previous steps have been completed and the InfiniBand adapters are correctly detected. If your InfiniBand devices are correctly configured, the output of the `ibv_devices` command will look similar to the following example:

```
# ibv_devices
---------- -----------
device node GUID
---------- -----------
ehca0 0002550010e56a00
ehca1 0002550010e56c00
```

b. Use `ibv_devinfo` to query the InfiniBand devices. Verify that the port status is active and that `sm_lid` is not 0 for all connected ports. The following example shows typical output from the `ibv_devinfo` command:

```
# ibv_devinfo

hca_id: ehca0
node_guid: 0002:5500:7018:9600
sys_image_guid: 0000:0000:0000:0000
vendor_id: 0x5076
vendor_part_id: 1
hw_ver: 0x2000021
phys_port_cnt: 2

port: 1
state: PORT_ACTIVE (4)
max_mtu: 4096 (5)
active_mtu: 4096 (5)
sm_lid: 1
port_lid: 29
port_lmc: 0x00

port: 2
state: PORT_ACTIVE (4)
max_mtu: 4096 (5)
active_mtu: 4096 (5)
sm_lid: 1
port_lid: 41
port_lmc: 0x00
```

Related concepts:

[Chapter 1, “Scope, requirements, and support,” on page 1](#)

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.

**Testing InfiniBand connectivity**

This series of tests assures connectivity, reasonable bandwidth, and latency performance between a pair of InfiniBand-connected nodes.

**Before you begin**

Configure the InfiniBand devices on all nodes, as described in “Configuring InfiniBand” on page 12.
About this task

Test the connectivity for each node with at least one other node in the cluster before you continue setting up the cluster.

These tests run between two nodes, one node acting as the server and the other node acting as the client for purposes of the test. The server node initiates a listening server and waits to receive requests from the client. The client node sends the request to the specified server.

The root user performs all the steps of this procedure.

Procedure

1. Test InfiniBand connectivity with the `ibv_rc_pingpong` command:
   a. Run the `ibv_rc_pingpong` command on the server node, as shown in the following example:
      ```
      compute_node1 # ibv_rc_pingpong
      local address: LID 0x001c, QPN 0x000033, PSN 0x150335
      ```
   b. Run the `ibv_rc_pingpong` command on the client node with the hostname of the server node as the parameter. In the following example, the hostname of the server node is `compute_node1`:
      ```
      compute_node2 # ibv_rc_pingpong compute_node1
      local address: LID 0x0016, QPN 0x000075, PSN 0x1fa58b
      remote address: LID 0x001c, QPN 0x000033, PSN 0x150335
      8192000 bytes in 0.02 seconds = 3601.08 Mbit/sec
      1000 iters in 0.02 seconds = 18.20 usec/iter
      ```
      If the connection is successful, the `ibv_rc_pingpong` process on the server will produce output indicating the connection from the client, and then exit. The following example shows output on the server that results from a successful connection:
      ```
      remote address: LID 0x0016, QPN 0x000075, PSN 0x1fa58b
      8192000 bytes in 0.02 seconds = 3584.34 Mbit/sec
      1000 iters in 0.02 seconds = 18.28 usec/iter
      ```

2. Test the bidirectional InfiniBand bandwidth with the `rdma_bw` command:
   a. On the server node, run `rdma_bw -b` as shown in the following example:
      ```
      # rdma_bw -b
      ```
   b. On the client node, run `rdma_bw -b` with the hostname of the server as the parameter. In the following example, the hostname of the listening server is `compute_node1`:
      ```
      # rdma_bw -b compute_node1
      15151: | port=18515 | ib_port=1 | size=65536 | tx_depth=100 | sl=0 | iters=1000 | \n      duplex=1 | cma=0 | 
      15151: Local address: LID 0x12, QPN 0x4377, PSN 0xb05218 RKey 0x679129 VAddr 0x00040000340000
      15151: Remote address: LID 0x11, QPN 0x447b, PSN 0xb085f6, RKey 0xa81105 VAddr 0x000400001a0000
      Warning: measured timestamp frequency 511.951 differs from nominal 4704 MHz
      15151: Bandwidth peak (#0 to #786): 3410.28 MB/sec
      15151: Bandwidth average: 3408.49 MB/sec
      15151: Service Demand peak (#0 to #786): 146 cycles/KB
      15151: Service Demand Avg : 146 cycles/KB
      ```
      The important item to check in this output is the Bandwidth average value. Throughput greater than 3000 MB/sec is desirable. A bandwidth average value of less than 3000 MB/sec may indicate a performance issue.
      ```
      Note: The other output and warnings can be safely ignored for the purposes of this test.
      ```

3. Test bidirectional InfiniBand latency with the `rdma_lat` command:
a. On the server node, run the `rdma_lat` command.

```
# rdma_lat
```

b. On the client node, run the `rdma_lat` command with hostname of the server as the parameter. The hostname of the listening server in the following example is `compute_node1`:

```
# rdma_lat compute_node1
local address: LID 0x12 QPN 0x43b2 PSN 0xb766cf RKey 0x67912e VAddr 0x00000010030001
remote address: LID 0x11 QPN 0x46f6 PSN 0xaaa5ce6 RKey 0xa8110b VAddr 0x00000010030001
Warning: measured timestamp frequency 511.938 differs from nominal 4704 MHz
Latency typical: 3.61665 usec
Latency best : 3.22695 usec
Latency worst : 28.9488 usec
```

The important item to check in this output is the `Latency typical:` value. A `Latency typical` value of less than 4.0 usec is desirable.

**Note:** The other output and warnings can be safely ignored.

**Related concepts:**

[Chapter 1, “Scope, requirements, and support,” on page 1](#)

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.
Chapter 4. Installing the Management Node

Install the TORQUE resource manager and the Maui Cluster Scheduler on the management node in order to control and track jobs on the compute nodes. Build special torque client and Machine Oriented Mini-server (MOM) packages to install on the compute nodes after you install the Torque and Maui software on the management node.

Related concepts:
Chapter 1, “Scope, requirements, and support,” on page 1

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.

Installing Torque resource manager

You install the TORQUE resource manager only on the management node. These instructions show how to obtain, build and install the newest version of the TORQUE software.

Before you begin

- Verify that the InfiniBand configuration is complete for all nodes by completing the tests in Testing InfiniBand connectivity on page 14.
- Ensure that the hpc user and the /home/hpc directory is set up on all nodes as described in Setting up the hpc user on page 10.

About this task

The root user on the management node performs all the steps of this procedure.

Procedure

1. As root user on the management node, download the newest version of TORQUE resource manager from http://www.clusterresources.com/downloads/torque

   In this example, torque.2.4.8 is the latest available package.

2. Extract, configure, and build the torque software package in the /usr/local/src directory. The following example shows this process and the appropriate flags to use when you configure for the 64-bit Power Architecture:

   ```
   # tar xzf torque-2.4.8.tar.gz -C /usr/local
   # cd /usr/local/torque-2.4.8
   # ./configure --enable-docs --with-scp --enable-syslog CFLAGS=-m64 --libdir=/usr/local/lib64
   # make
   # make install
   # ldconfig
   ```

3. Initialize the torque server by running the setup script and indicating the root user:

   ```
   # ./torque.setup root
   initializing TORQUE (admin: root@compute_node1.example.com)
   Max open servers: 4
   Max open servers: 4
   ```

4. Verify that the /var/spool/torque/server_name file contains the fully qualified host name of the management node.

   Note:
a. A short host name will also work if all the nodes in the cluster share the same name server. This should be created during the initialization step.

b. The /var/spool/torque/server_name file was created by the `torque.setup` command.

```bash
# cat /var/spool/torque/server_name
mgmt_node.example.com
```

5. Build the Torque self-extracting packages for compute nodes. The following example shows the root user running make packages:

```bash
# make packages
```

6. Copy the self-extracting packages you built for the compute nodes into the /home/hpc/comput-node-files directory, as shown in the following example:

```bash
Note: You must create the /home/hpc/compute-node-files directory if it doesn't already exist.
# mkdir /home/hpc/compute-node-files
# cp *.sh /home/hpc/compute-node-files/
```

7. Run the `libtool` command as shown in the following example to configure the libraries for the management node.

```bash
# libtool --finish /usr/local/lib64
```

Results

You will use these packages in “Preparing the TORQUE packages for the compute nodes” on page 20.

Related concepts:

- Chapter 1, “Scope, requirements, and support,” on page 1

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.

### Installing Maui cluster scheduler

The Maui server controls job scheduling across the cluster. These instructions show how to obtain, build, and install the newest version of the Maui cluster scheduler on the management node of the cluster.

#### Before you begin

Ensure that the TORQUE server is installed on the management node, as described in Installing the TORQUE resource manager.

#### About this task

The root user on the management node performs all the steps of this procedure.

#### Procedure


   *Note:* you must register in order to download the software

   For our example, we selected the Maui 3.3 version, the newest version as of the writing of this document.

2. Extract, configure, and build the Maui server software using the following commands:
# tar -zxf maui-3.3.tar.gz -C /usr/local/src
# cd /usr/local/src/maui-3.3
# chmod +x /usr/local/torque-2.4.8/pbs-config
# ./configure --with-pbs=/usr/local CFLAGS=-m64 LDFLAGS=-m64
# make
# make install

3. Add the /usr/local/maui/bin directory to the PATH environment variable for the hpc user by appending the contents of the /usr/local/src/maui-3.3/etc/maui.sh file to the /home/hpc/.bashrc file.

    # cat /usr/local/src/maui-3.3/etc/maui.sh >> /home/hpc/.bashrc
    # cp /usr/local/src/maui-3.3/etc/maui.sh /home/hpc/compute-node-files/

4. Set up the Maui daemon as a service on the management node server:
   a. Edit the /usr/local/src/maui-3.3/etc/maui.d file and change the value of the MAUI_PREFIX variable to /usr/local/maui as shown in the following example:

        MAUI_PREFIX=/usr/local/maui
   b. Copy the /usr/local/src/maui-3.3/etc/maui.d file to /etc/init.d/maui.d, as shown in the following example:

        # cp /usr/local/src/maui-3.3/etc/maui.d /etc/init.d/maui.d

5. Edit the /usr/local/maui/maui.cfg file, which was created by the build process, to include the information needed for the environment of your hpc cluster:
   a. Make sure the following lines are included as follows:

        SERVERPORT 42599
        ADMIN1 root hpc
        ADMIN3 ALL

   b. Modify the SERVERHOST and ADMINHOST lines to contain the fully qualified host name for the management node. For example, if the fully qualified host name of your management node is mgmt_node.example.com, edit these lines as shown in the following example:

        SERVERHOST mgmt_node.example.com
        ADMINHOST mgmt_node.example.com

   c. Verify that the RMCFG line contains the short host name in brackets, as shown in the following example:

        RMCFG[mgmt_node] TYPE=PBS

6. Create the /var/spool/torque/server_priv/nodes file to contain a list of all of the compute nodes in the cluster:

    # cd /var/spool/torque/server_priv
    # vi nodes

   a. Use a text editor to add one line to the /var/spool/torque/server_priv/nodes file for each compute node in your cluster. Use the np parameter to define the number of CPU threads that are available for use on each node. For example, we have two compute nodes we are defining, each with 64 threads available:

        compute_node1.example.com np=64
        compute_node2.example.com np=64

   b. Copy the /var/spool/torque/server_priv/nodes file to the /home/hpc/compute-node-files/ directory:

        # cp /var/spool/torque/server_priv/nodes /home/hpc/compute-node-files

7. Set up Maui as a service on the management node using the chkconfig command, as shown in the following example:

    # chkconfig --add maui.d
    # chkconfig --level 3456 maui.d on
    # chkconfig --list maui.d

    maui.d 0:off 1:off 2:off 3:on 4:on 5:on 6:on

8. Start the Maui service on the management node as shown in the following example:
Set up the TORQUE server on the management node by copying the pbs_server file to the /etc/init.d/ directory, as shown in the following example:

```
# cd /usr/local/torque-2.4.8
# cp -p contrib/init.d/pbs_server /etc/init.d/
```

10. Add the pbs_server service to the management node with the `chkconfig` command, as shown in the following example:

   ```
   Note: The pbs_server service is the TORQUE resource manager service.
   # chkconfig --add pbs_server
   # chkconfig --level 3456 pbs_server on
   # chkconfig --list pbs_server
   pbs_server 0:off 1:off 2:off 3:on 4:on 5:on 6:on
   ```

11. Restart the pbs_server service on the management node in order to allow changes to take effect. The pbs_server service starts the batch server on the management node that will pick up any jobs. You can start the pbs_server service as shown in the following example:

   ```
   # service pbs_server restart
   Starting TORQUE Server: [ OK ]
   ```

Results

The TORQUE and Maui services are installed and running on the management node. You can query the TORQUE queue and server attributes with the `qmgr -c 'p s'` command.

Related concepts:

- Chapter 1, “Scope, requirements, and support,” on page 1

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.

Preparing the TORQUE packages for the compute nodes

You must create Torque Resource Manager installation packages for the compute nodes before you can configure the Machine Oriented Mini-server on the compute nodes.

Before you begin

Ensure that you have completed all of these prerequisite tasks:

- Build and install the Torque and Maui packages on the management node.
- Build the self-extracting installation packages and copy them to the `/home/hpc/compute-node-files` directory on the management node.
- Create the hpc user on the compute nodes as described in “Setting up the hpc user” on page 10.

About this task

The root user on the management node performs these steps.

Procedure

1. Create the `/usr/local/torque-2.4.8/mom_priv-config` file on the management node:

   ```
   Note: You will copy this temporary file to the `/home/hpc/compute-node-files` directory.
   a. Provide the following information in the `/usr/local/torque-2.4.8/mom_priv-config` file:
      - IP address of the pbsserver, (the same as the IP address of the management node)
   ```
• IP address of the clienthost, (the same as the IP address of the management node)
• Settings for important directories that are used by the Machine Oriented Mini-server

The following example of the `mom_priv-config` file content shows how to format this information.

**Note:** The IP address for your management node is specific to your environment. The rest of the file must be the same as this example if you have configured your hpc user as described in this document.

```
$pbservr  x.x.x.x  # (IP address of management node)
$clienthost  x.x.x.x  # (IP address of management node)
$usecp   */home/hpc  /home/hpc
$usecp   */home  /home
$usecp   */root  /root
$usecp   */tmp.scratch  /tmp.scratch
$tmpdir   /tmp
```

b. Copy the `/usr/local/torque-2.4.8/mom_priv-config` file to the `/home/hpc/compute-node-files` directory.

2. Prepare for the configuration of the pbs_mom service on each compute node. The `pbs_mom` command starts a batch Machine Oriented Mini-server that will control job execution as directed by the TORQUE resource manager service, usage limits, and notifications.

   a. Update `/usr/local/torque-2.4.8/contrib/init.d/pbs_mom` file on the management node by adding `ulimit -l unlimited` as shown in the following example `pbs_mom` file:

   ```
   #!/bin/sh
   #
   # pbs_mom  This script will start and stop the PBS Mom
   #
   # chkconfig: 345 95 5
   # description: TORQUE/PBS is a versatile batch system for SMPs and clusters
   #
   ulimit -n 32768
   ulimit -l unlimited  # <--- add this line
   # Source the library functions
   . /etc/rc.d/init.d/functions
   ```

   b. Copy the `/usr/local/torque-2.4.8/contrib/init.d/pbs_mom` to the `/home/hpc/compute-node-files` directory.

   c. Use the `cp -p` command to preserve mode and ownership of the file as shown in the following example:

   ```
   # cp -p contrib/init.d/pbs_mom /home/hpc/compute-node-files/
   ```

3. Copy the `/home/hpc/compute-node-files` directory as an archive file from the management node onto each of the compute nodes:

   a. Create a tar archive of the contents of the `/home/hpc/compute-node-files` directory, as shown in the following example:

   ```
   # cd /home/hpc
   # tar zcvf compute-node-files.tar.gz compute-node-files
   ```
b. Copy the archive to the /home/hpc directory on each compute node. In the following example there are two compute nodes in the cluster, with the host names compute_node1 and compute_node2:

```
# scp compute-node-files.tar.gz compute_node1:/home/hpc
# scp compute-node-files.tar.gz compute_node2:/home/hpc
```

**Results**

You are ready to extract and install the TORQUE packages on each compute node.

**Related concepts:**

Chapter 1, “Scope, requirements, and support,” on page 1

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.

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### Configuring TORQUE on the compute nodes

In order to use the Torque Resource Manager to control jobs in the cluster, you need to configure the Machine Oriented Mini-server on each compute node.

**Before you begin**

Complete the procedure described in “Preparing the TORQUE packages for the compute nodes” on page 20.

**About this task**

You need to follow these steps on each compute node.

The root user on the compute node performs this procedure.

**Procedure**

1. Extract the compute-node-files.tar.gz archive and install each TORQUE package as shown in the following example:

```
# cd /home/hpc
# tar zxf compute-node-files.tar.gz
# cd compute-node-files/
# ./torque-package-clients-linux-powerpc64.sh --install

Installing TORQUE archive...

Done.
```

```
# ./torque-package-mom-linux-powerpc64.sh --install

Installing TORQUE archive...

Done.
```

2. Copy the Machine Oriented Mini-server files to the appropriate directories with the following commands:

```
# cp /home/hpc/compute-node-files/mom_priv-config /var/spool/torque/mom_priv/config
# cp /home/hpc/compute-node-files/pbs_mom /etc/init.d/
```

3. Prepare the pbs_mom service with the following commands:
4. Start the pbs_mom service with the following command:
   
   # chkconfig --add pbs_mom
   # chkconfig --level 3456 pbs_mom on
   # chkconfig --list pbs_mom

**Related concepts:**

Chapter 1, “Scope, requirements, and support,” on page 1

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.

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**Validating job submissions**

Verify that TORQUE resource manager and Maui Cluster Scheduler are properly configured by submitting a basic test job and a multi-node test job.

**Before you begin**

Ensure that you have completed the following tasks:

- "Installing Maui cluster scheduler” on page 18
- "Installing Torque resource manager” on page 17
- “Preparing the TORQUE packages for the compute nodes” on page 20
- “Configuring TORQUE on the compute nodes” on page 22

Restart the operating system on each node.

**About this task**

The hpc user submits the test jobs on the cluster.

**Note:** The root user cannot submit the jobs on the cluster because of the TORQUE security controls.

The job basic job test and multi-node job test verify resource handling and job scheduling on your nodes.

**Procedure**

1. Verify that the Maui and TORQUE services are running with the following steps. Because the torque and maui software have been configured as services, the processes should automatically start after rebooting.
   
   a. On the management node, verify that the maui service and the pbs_server service are running.
      
      When these services are running, you can see output from the ps command similar to the output shown in the following example:
      
      ```
      # ps -ef | grep -E "pbs|maui"
      root  4091  1  0 11:16 ?  00:00:00 /usr/local/maui-3.3/sbin/maui
      root  4525  1  0 11:16 ?  00:00:00 /usr/local/sbin/pbs_server
      root  7253  7077  0 11:28 pts/1 00:00:00 grep -E pbs|maui
      ```
      
      b. On the compute nodes, verify that the pbs_mom service is running. When this service is running, you can see output from the ps command similar to the output shown in the following example:
      
      ```
      # ps -ef | grep pbs
      root  4467  1  0 11:16 ?  00:00:00 /usr/local/sbin/pbs_mom -p
      root  7144  7046  0 11:26 pts/1 00:00:00 grep pbs
      ```
   
   2. Perform a basic job test on the management node with the following steps:
      
      a. Submit the job using the qsub command and view the status of the job using the qstat command as the hpc user on the management node, as shown in the following example:
The output of the `qstat` command shows the following characteristics of the job:

**Job id**  The Job id field shows the ID associated with the job and the node where the job is running. The ID of the job running on the mgmt_node node in this example is 1.

**Name**  The Name field shows the name defined on the #PBS -N line in the PBS job file. If no job name is defined in the PBS job file, the default value of the Name field is the file name of the job. In this example, the job is from standard input, so the job name is STDIN.

**User**  The User field shows the name of the user that submitted the job.

**Time Use**  The Time Use field shows the amount of CPU time used by the job.

**S**  The S field shows the status of the job. In this example, the value of the S field is R, indicating that the job is running. When the job is complete, the value of the status field is C.

**Note:** If the value of the status column is Q (queued) when you run this test job, there is probably a configuration issue. If this occurs, review the installation and configuration steps to ensure they were completed correctly.

**Queue**  The Queue field shows the name of the queue that is handling the job. In this example, the job is the queue named batch.

3. To verify that the cluster is configured correctly, use the `mpirun` command to run the `hostname` command on each node to ensure that processes run successfully on each node. The parameters used in the following example with the `mpirun` command are:
   - The `-np` flag specifies the total number of copies of the process to run on the nodes.
   - The `-host` flag specifies the host names where the process will run.
   - The last parameter of the `mpirun` command is the command to run on the nodes.

   The following example shows how to use the `mpirun` command to run a simple process on all the nodes of your cluster.

   ```bash
   $ mpirun -np 2 --host compute_node1.example.com,compute_node2.example.com hostname
   compute_node1.example.com
   compute_node2.example.com
   ```

   If the `hostname` command runs successfully on each node, the host name of each node appears in the output of the `mpirun` command shown in this example. In this example, the output shows the host names of the two compute nodes in the test cluster, `compute_node1`, and `compute_node2`.

4. Perform a simple multi-node test using a PBS script with the following steps:
   a. On the management node, create a PBS script similar to the following example. Note the following in the example:
      - The lines beginning with the number sign (#) in the PBS script are TORQUE directives and are used to set TORQUE environment variables for the job.
      - In the following example, the file name of the PBS script is `multinode.pbs`.
      - In the following example, the host names of the compute nodes are `compute_node1` and `compute_node2`.
      - In the following example, the `-np` flag of the `mpirun` command is used to specify that two copies of the `hostname` command will run.
#PBS -N node_test
#PBS -q batch
#PBS -l nodes=2,pmem=100m,walltime=00:30:00
#PBS -M admin@example.com
#PBS -m e
#PBS -V

mpirun -np 2 --host compute_node1,compute_node2 hostname

b. Submit the PBS script as the hpc user on the management node, and check the status of the job as shown in the following example:

$ qsub multinode.pbs
11.mgmt_node.example.com
[hpc@mgmt_node ~]$ qstat

<table>
<thead>
<tr>
<th>Job id</th>
<th>Name</th>
<th>User</th>
<th>Time</th>
<th>Use</th>
<th>Queue</th>
</tr>
</thead>
<tbody>
<tr>
<td>1.mgmt_node</td>
<td>node_test</td>
<td>hpc</td>
<td>00:00:00</td>
<td>C</td>
<td>batch</td>
</tr>
</tbody>
</table>

This example shows a job submission, the returned job number (1), and the qstat output which indicates whether the job is running or has already completed.

Related concepts:

- Chapter 1, “Scope, requirements, and support,” on page 1

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.
Chapter 5. Installing additional advanced software

There are several advanced software packages you can use to enhance the capability of compute nodes for a POWER processor-based cluster. This discussion includes basic installation and configuration instructions for libhugetlbfs, the IBM Advance Toolchain for PowerLinux, the ATLAS math libraries, and the IBM XL C/C++ and IBM XL Fortran compilers.

Related concepts:
Chapter 1, “Scope, requirements, and support,” on page 1

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.

Installing libhugetlbfs

You can boost performance for some HPC workloads by using 16MB huge pages provided by the libhugetlbfs library.

About this task

You must install and configure all nodes (including the management node) because the libhugetlbfs environment variables are applied on the management node for jobs that run on the compute nodes.

The root user performs all the steps of this task.

Procedure

1. Download the newest libhugetlbfs library from the project home, at the following URL:
   http://sourceforge.net/projects/libhugetlbfs/files/
2. Prepare and install the library. Note that libhugetlbfs build process will create both the 32-bit and the 64-bit versions on the Power architecture.
   a. Extract the archive file, as shown in the following example:
      
      ```
      # tar -C /usr/local/src -zxf libhugetlbfs-2.9.tar.gz
      ```
   b. Change to the top-level directory of the extracted source, as shown in the following example:
      
      ```
      # cd /usr/local/src/libhugetlbfs-2.9/
      ```
   c. Build and install the software package, as shown in the following example:
      
      ```
      # make
      # make install PREFIX=/usr/local
      ```
3. Create and mount the /libhugetlbfs file system.
   
   ```
   # mkdir /libhugetlbfs
   # mount -t hugetlbfs hugetlbfs /libhugetlbfs
   ```
4. Give the hpc user group privileges to use /libhugetlbfs.
   a. Create the libhuge group, as shown in the following example:
      
      ```
      # groupadd libhuge
      ```
   b. Make the hpc user a member of the libhuge group, as shown in the following example:
      
      ```
      # usermod -a -G libhuge hpc
      ```
   c. Give the libhuge group privileges to use the /libhugetlbfs directory and set the permissions as shown in the following example:
      
      ```
      # chgrp libhuge /libhugetlbfs
      # chmod 777 /libhugetlbfs
      ```
5. Reserve huge pages for compute jobs to use, by providing the number of desired pages in the
   `nr_hugepages` file. Clear any existing huge pages before you reserve a new number of huge pages, as
   shown in the following example:
   ```
   # echo 0 > /proc/sys/vm/nr_hugepages
   # echo 100 > /proc/sys/vm/nr_hugepages
   ```

6. Validate the configuration of `libhugetlbfs`.
   a. Verify that the permissions of the `/libhugetlbfs` file system are set correctly, as shown in the
      following example:
      ```
      # ls -ld /libhugetlbfs/
      drwxrwxrwx 2 root libhuge 0 Oct 8 20:40 /libhugetlbfs/
      ```
   b. Verify that the `libhuge` ld scripts are located in the directory where `libhugetlbfs` is installed, as
      shown in the following example:
      ```
      ls /usr/local/share/libhugetlbfs/
      ld ld.hugetlbfs ldscripts
      ```
   c. Verify that the correct number of huge pages is allocated by checking `/proc/meminfo` as shown in
      the following example:
      ```
      # cat /proc/meminfo | grep Huge
      ```

7. Make the settings for `libhugetlbfs` persistent by having the configuration occur when the node starts
   up.
   a. Edit the `/etc/fstab` file to include the following line:
      ```
      hugetlbfs /libhugetlbfs libhugetlbfs mode=0777,gid=1000 0 0
      ```
      **Note:** The group ID for the libhuge group in this example is 1000. Verify the libhuge group ID by
      running the `id` command as the hpc user.
   b. Edit the `/etc/sysctl.conf` file to include the following parameters:
      ```
      vm.nr_hugepages=0
      vm.nr_hugepages=100
      ```
   c. Run the `sysctl -p` command to load settings from the default sysctl configuration file,
      `/etc/sysctl.conf`.

**Results**

When you have completed this process for each node, you can use 16MB huge pages on your cluster.

**Related concepts:**
- Chapter 1, “Scope, requirements, and support,” on page 1

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint,
including the intended audience, the scope and purpose, the hardware and software requirements for the
tasks detailed in this blueprint, and the types of support available to you.

### Installing IBM Advance Toolchain for PowerLinux

The IBM Advance Toolchain for PowerLinux provides potential performance benefits by using newer
open source compilers and runtime libraries than those that are provided in most Linux distributions.

**About this task**

If you determine that your applications will benefit from the IBM Advance Toolchain for PowerLinux,
perform this process on each node of the cluster.

The root user performs the installation process.

The hpc user must perform some of the validation steps.
Procedure

1. Download the three IBM Advance Toolchain for PowerLinux 3.0 RPM packages for Red Hat Enterprise Linux from the following URL: [ftp://linuxpatch.ncsa.uiuc.edu/toolchain/at/at3.0/redhat/RHEL5](ftp://linuxpatch.ncsa.uiuc.edu/toolchain/at/at3.0/redhat/RHEL5)

   The following list shows the names of the specific files to download:
   - advance-toolchain-at3.0-runtime-3.0-0.ppc64.rpm
   - advance-toolchain-at3.0-devel-3.0-0.ppc64.rpm
   - advance-toolchain-at3.0-perf-3.0-0.ppc64.rpm

2. Install the RPM packages in the order shown in the following example:

   # rpm -i advance-toolchain-at3.0-runtime-3.0-0.ppc64.rpm
   # rpm -i advance-toolchain-at3.0-devel-3.0-0.ppc64.rpm
   # rpm -i advance-toolchain-at3.0-perf-3.0-0.ppc64.rpm

   The default installation location for the IBM Advance Toolchain for PowerLinux is the `/opt/at3.0/` directory. The IBM Advance Toolchain for PowerLinux gcc compilers are installed in the `/opt/at3.0/bin` directory by default.

3. Run the `createldhuge` script to configure IBM Advance Toolchain for PowerLinux to work with libhugetlbfs, as shown in the following example:

   # /opt/at3.0/scripts/createldhuge.sh
   /usr/local/share/libhugetlbfs/ld.hugetlbfs /opt/at3.0/

4. Confirm the version of the gcc command installed by the Linux distribution is the gcc executable provided by the Linux distribution.

   # which gcc
   /usr/bin/gcc

5. Make the IBM Advance Toolchain for PowerLinux gcc available for the hpc user.

   a. Add the IBM Advance Toolchain for PowerLinux bin directory in the PATH environment variable for the hpc user so that the hpc user will use this version of the gcc command by default, as shown in the following example:

      # su - hpc
      $ export PATH=/opt/at3.0/bin:$PATH

   b. Verify that the IBM Advance Toolchain for PowerLinux version of gcc is now the default gcc command used by the hpc user, as shown in the following example:

      $ which gcc
      /opt/at3.0/bin/gcc

Results

If you complete this process on all the nodes, the cluster is configured to use the IBM Advance Toolchain for PowerLinux with libhugetlbfs.

Related concepts: [Chapter 1, “Scope, requirements, and support,” on page 1](#)

Installing the IBM XL C/C++ and Fortran compilers

Users who want the advantages of optimized compilers may benefit from the IBM XL compilers.

Before you begin

You can find more information about getting a license for these compilers at the following web sites:


Note: Users can also take advantage of the free 60-day trial for the IBM XL compilers. Here we provide instructions on how to download and install the trial versions.

You must ensure that the required compiler toolchain packages from the Linux distributor are installed on the system before you install the IBM XL compilers. You can do this with the `yum install` command as shown in the following example:

```
# yum install gcc gcc-c++ glibc.ppc glibc.ppc64 glibc-devel.ppc glibc-devel.ppc64 \
libgcc.ppc libgcc.ppc64 libstdc++.ppc libstdc++.ppc64 libstdc++-devel.ppc \
libstdc++-devel.ppc64 perl
```

About this task

If you choose to use the XL C/C++ and XL Fortran compilers, perform this process on each node of the cluster.

The root user performs the installation process.

**Procedure**

1. Download the XL compiler trial versions from the following URLs:

   **Note:** You have to accept the license agreement for both compilers before you can go to the Download using http tab and click **Download now** to download the compiler archive files.

2. Install the XL C/C++ compiler.
   a. Prepare and install the XL C/C++ compiler from the directory where you extract the archive file, as shown in the following example. This process will install the compiler in the `/opt/ibmcmp/` directory by default:
      ```
      mkdir /usr/local/src/xlc
      # tar -C /usr/local/src/xlc -zxf xlc.11.1.0.0.linux.eval.tar.gz
      # cd /usr/local/src/xlc/
      # ./xlc_install -rpmloc images/rpms/
      The following example output shows the portions of the **xlc_install** command output that you need to interact with the installation process. The places where output was omitted from this example are indicated by the three periods ("..."):
      Press Enter to continue viewing the license agreement, or, Enter "1" to accept the agreement, "2" to decline it or "99" to go back to the previous screen, "3" Print, "4" Read non-IBM terms.
      
      1
      ...
      
      Link Source
      =========== ===========
      /usr/bin/gxlc /opt/ibmcmp/vacpp/11.1/bin/gxlc
      /usr/bin/gxlc++ /opt/ibmcmp/vacpp/11.1/bin/gxlc++
      /usr/bin/gxlC /opt/ibmcmp/vacpp/11.1/bin/gxlC
      /usr/bin/xlc /opt/ibmcmp/vacpp/11.1/bin/xlc
      /usr/bin/xlc++ /opt/ibmcmp/vacpp/11.1/bin/xlc++
      /usr/bin/xlC /opt/ibmcmp/vacpp/11.1/bin/xlC
      /usr/bin/xlc_r /opt/ibmcmp/vacpp/11.1/bin/xlc_r
      /usr/bin/xlc++_r /opt/ibmcmp/vacpp/11.1/bin/xlc++_r
      /usr/bin/xlC_r /opt/ibmcmp/vacpp/11.1/bin/xlC_r
      ```
      
      30  Blueprints: Setting up an HPC cluster with Red Hat Enterprise Linux
Do you want to proceed with the symbolic links?
Please type "yes" or "no": yes

Installation Completed.
Filename of the installation log: /opt/ibmcmp/vacpp/11.1/xlc_install.log

b. Run the `xlc` command to verify that you see the compiler information page, as shown in the following example:
```
# xlc
xlc(1) IBM XL C/C++ for Linux, V11.1 xlc(1)
```

NAME
xlc, xlc++, xlC, cc, c89, c99 and related commands - invoke the IBM XL
C/C++ compiler.

SYNTAX
```
<invocation-command> [ <option> | <inputfile> ]
```

3. Install the XL Fortran compiler.

a. Prepare and install the XL Fortran compiler from the directory where you extract the archive file, as shown in the following example. This process will install the compiler in the /opt/ibmcmp/ directory by default:
```
# mkdir /usr/local/src/xlf
# tar -C /usr/local/src/xlf -zxf xlf.13.1.0.0.linux.eval.tar.gz
# cd /usr/local/src/xlf/
# ./xlf_install -rpmloc images/rpms/
```
The following example output shows the portions of the `xlf_install` command output which you need to interact with the installation process. The places where output was omitted from this example are indicated by the three periods ("..."):  
Type "yes" even if you have "IBM XL SMP Version 2.1.0.0-100630 for Linux", "IBM XL MASS Version 6.1.0.0-100630 for Linux" already installed at the default installation path.
Do you want to proceed with the installation?
Please type "yes" or "no": yes

Press Enter to continue viewing the license agreement, or, Enter "1" to accept the agreement, "2" to decline it or "99" to go back to the previous screen, "3" Print, "4" Read non-IBM terms.

1

Do you want to proceed with the symbolic links?
Please type "yes" or "no": yes

Installation Completed.
Filename of the installation log: /opt/ibmcmp/xlf/13.1/xlf_install.log

b. Run the `xlf` command to verify that you see the compiler information page, as shown in the following example:
```
# xlf
xlf(1) IBM XL Fortran for Linux, V13.1 xlf(1)
```

NAME
xlf, xlf_r, f77, fort77, xlf90, xlf90_r, f90, xlf95, xlf95_r, f95,
xlf2003, xlf2003_r, f2003 - invoke the IBM XL Fortran compiler.

SYNTAX
```
<invocation-command> [ <option> | <inputfile> ]
```

Results

If you complete this process on all the nodes of your cluster, the XL C/C++ and XL Fortran compilers are installed and ready to use.

Related concepts:

Chapter 1, “Scope, requirements, and support,” on page 1

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.

Installing ATLAS math libraries

Automatically Tuned Linear Algebra Software (ATLAS) is a math library that can be used to compile workloads such as Linpack and HPC Challenge.

Before you begin

Download the newest stable version of ATLAS, which is 3.8.3 at the time this paper was written:
http://sourceforge.net/projects/math-atlas/files/

Note: At the time this document was written, the newest stable version was ATLAS 3.8.3, which is used in the examples in this document.

About this task

The build process takes several hours to complete, so you may prefer to compile the software on one node and copy the compiled versions to your other nodes with the identical processor architecture.

The root user performs all the steps of this process.

Procedure

1. Extract the ATLAS tar archive file, as shown in the following example:
   
   # tar -jxf atlas3.8.3.tar.bz2 -C /usr/local/

2. Configure the ATLAS setup.
   
   As root, go into the top level ATLAS directory and create a build directory where you will run the configure and make commands, as shown in the following example:
   
   # cd /usr/local/ATLAS/
   # mkdir obj64
   # cd obj64/
   # ../configure -b 64
   
   The example uses a directory called obj64 as the 64-bit library build location.
   
   • The example uses a directory called obj64 as the 64-bit library build location.
   
   • The -b 64 option tells the ATLAS configure command to build the 64-bit libraries.

3. Run the make step to build, test, and optimize the library.

   Note: This step may take several hours to complete. The ATLAS math libraries employ a self-tuning automated optimization process of building, running, assessing the results, and using the best options. The following example shows the invocation of the make command, and modified output with the last several lines of message produced by the make command. The omitted lines of output are represented by a line containing three periods (“...”) in the example output.
   
   # make
   ...
   ATLAS install complete. Examine
   ATLAS/bin/<arch>/INSTALL_LOG/SUMMARY.LOG for details.
   make[1]: Leaving directory `/usr/local//ATLAS/obj64'
make clean
make[1]: Entering directory `/usr/local/ATLAS/obj64'
rm -f *.o x* config?.out *core*
make[1]: Leaving directory `/usr/local/ATLAS/obj64'

4. After the **make** command completes, run the **make check** command to check the libraries. This command produces a report showing a list of tests that either pass or fail. Ensure that all of the tests pass.

5. Install the libraries. The following example shows a listing of the libraries that the **make install** command installs in the `/usr/local/ATLAS/obj64/lib/` directory:

```
# make install
# ls lib/
libatlas.a libf77blas.a lltcbblas.a  libstatlas.a  Make.inc
libblas.a liblapack.a libftblas.a  Makefile
```

**Results**

After you install the ATLAS libraries on the nodes of the cluster, the libraries are ready to use.

**Example**

The order you use to link to the ATLAS libraries can affect how they function. The ATLAS FAQs provide more information about this subject. The following example shows a correct order to link the libraries:

```
-lc  -L/usr/local/ATLAS/obj64/lib/  -llapack -lltcbblas -lltfblas -latlas
```

**Related concepts:**

Chapter 1, “Scope, requirements, and support,” on page 1

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.
Chapter 6. Building specialized versions of Open MPI

You can configure Open MPI to integrate better and make better use of other components in an HPC software stack.

Open MPI is highly configurable both at build time and at run time. Although Open MPI will function well on POWER-based systems as installed from the IBM Installation Toolkit, you can optimize Open MPI to work better with other software that is installed on the HPC cluster. This topic discusses methods to configure Open MPI to work better with various software components that are discussed in this blueprint. Specifically, this discussion covers integrating the following packages with Open MPI:

- TORQUE resource manager
- IBM Advance Toolchain for PowerLinux
- IBM XL C/C++ and Fortran compilers
- libhugetlbfs

Related concepts:
Chapter 1, “Scope, requirements, and support,” on page 1

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.

Building Open MPI with TORQUE

Configuring Open MPI to work directly with the TORQUE resource manager can simplify launching and managing MPI jobs across a set of resources.

Before you begin

Ensure that the TORQUE resource manager is installed on the nodes in your cluster, as described in Chapter 4, “Installing the Management Node,” on page 17.

About this task

The hpc user performs most of the steps in this task.

The root user performs the build and installation processes in this task.

This procedure can be used to install any new versions of Open MPI.

The process shows how to build and make the package on the management node. You can then create a tar archive file of the /usr/local/openmpi library and then copy the archive file to each compute node and then extract the files. After these steps, you must change the PATH and LD_LIBRARY settings in the .bashrc file to use the new library.

Procedure

1. On the management node, download the latest Open MPI source tar file in the 1.4.x release series from the following location: http://www.open-mpi.org/software/ompi/v1.4/

   Note: This example, uses Open MPI version 1.4.2, which is the latest stable release of Open MPI at the time of this writing.

2. As the root user on the management node, extract the sources and go to the source directory, as shown in the following example:
3. On the management node, configure and build a Torque-knowledgeable version of Open MPI. Do this by using the `--with-tm` flag for the configure script. Specifically, set the value of the `--with-tm` flag to the directory location where Open MPI can reference `include/tm.h`. If you have followed the instructions in this blueprint so far, the directory to use is `/usr/local/torque-2.4.8/src` as shown in the following example. After the configure step, run the `make` command and the `make install` command.

```bash
#./configure --prefix=/usr/local/openmpi-1.4.2-tm \
--with-platform=contrib/platform/ibm/optimized-ppc64-gcc --with-tm=/usr/local/torque-2.4.8/src
# make
# make install
```

4. On the management node, update the relevant environment variables of the hpc user to enable use of the TORQUE resource manager-aware version of Open MPI as shown in the following example:

```bash
# su - hpc
$ export PATH=/usr/local/openmpi-1.4.2-tm/bin:$PATH
$ export LD_LIBRARY_PATH=/usr/local/openmpi-1.4.2-tm/lib:$LD_LIBRARY_PATH
```

**Note:** You may also remove the previous version of Open MPI from PATH and LD_LIBRARY_PATH. However the syntax in this example sets the updated library to be found first in the path, so any older library in the path has no effect.

You can use the following example to make these updates to the `.bashrc` file:

```bash
$ cat >> /home/hpc/.bashrc <<EOF
export PATH=/usr/local/openmpi-1.4.2-tm/bin:$PATH
export LD_LIBRARY_PATH=/usr/local/openmpi-1.4.2-tm/lib:$LD_LIBRARY_PATH
EOF
```

5. On the management node, run `OMPI_INFO` and use the `grep` command to retrieve the lines containing "plm" to ensure that the new build of Open MPI has TORQUE integration. If the TORQUE manager component built correctly, you will see the tm entry listed as a component of the plm (Process Launch Module) framework, as shown int the following example:

```bash
$ ompi_info | egrep plm:
MCA plm: rsh (MCA v2.0, API v2.0, Component v1.4.2)
MCA plm: slurm (MCA v2.0, API v2.0, Component v1.4.2)
MCA plm: tm (MCA v2.0, API v2.0, Component v1.4.2)
```

6. On the management node, as the root user, prepare the tar archive file of the `openmpi-1.4.2-tm` directory contains the updated Open MPI library, and distributed the archive to all of the compute nodes, as shown in the following example:

```bash
# cd /usr/local
# tar cvf openmpi-1.4.2-tm.tar openmpi-1.4.2-tm
# scp openmpi-1.4.2-tm.tar compute_node1:/usr/local/
# scp openmpi-1.4.2-tm.tar compute_node2:/usr/local/
```

**Note:** In this example, the compute nodes are named compute_node1 and compute_node2.

7. On each of the compute nodes, install the TORQUE resource manager-aware version of Open MPI, and set up the environment for the hpc user.

a. As the root user on each compute node, extract the tar archive, as shown in the following example

```bash
# cd /usr/local
# tar xvf openmpi-1.4.2-tm.tar
```

b. As the hpc user on each compute node, configure the appropriate environment variables, as shown in the following example:

```bash
$ export PATH=/usr/local/openmpi-1.4.2-tm/bin:$PATH
$ export LD_LIBRARY_PATH=/usr/local/openmpi-1.4.2-tm/lib:$LD_LIBRARY_PATH
```

You can use the following example to make these updates to the `.bashrc` file:
c. On each compute node, run `ompi_info` and use the `grep` command to retrieve the lines containing "plm" to ensure that the new build of Open MPI has TORQUE integration as shown in the following example:

```
$ ompi_info | egrep plm:
  MCA plm: rsh (MCA v2.0, API v2.0, Component v1.4.2)
  MCA plm: slurm (MCA v2.0, API v2.0, Component v1.4.2)
  MCA plm: tm (MCA v2.0, API v2.0, Component v1.4.2)
```

### Configuring Open MPI for use with IBM Advance Toolchain for PowerLinux

You can configure Open MPI for use with IBM Advance Toolchain for PowerLinux with a single command string.

#### Before you begin

Ensure that the Open MPI and the IBM Advance Toolchain for PowerLinux RPMs are installed on the system.

#### About this task

The following procedure should be completed on all nodes.

#### Procedure

1. Adjust the PATH environment variable so that the Advance Toolchain installation bin directory is at the head of the PATH list, as shown in the following example:

   ```
   $ export PATH=/opt/at3.0/bin:$PATH
   $ export PATH=/usr/local/openmpi-1.4.2-tm/bin:$PATH
   $ export LD_LIBRARY_PATH=/usr/local/openmpi-1.4.2-tm/lib:$LD_LIBRARY_PATH
   EOF
   ```

   Once this is done, all builds done with the Open MPI wrapper compilers (such as mpicc, mpi90, and so on), regardless of which Open MPI build you are using, will use the compilers and runtime environment provided by the IBM Advance Toolchain for PowerLinux.

2. Validate the use of IBM Advance Toolchain for PowerLinux with the following steps:

   a. Run the `which gcc` command and ensure that the `gcc` used is coming from the `/opt/at3.0/bin` directory, as shown in the following example:

   ```
   $ which gcc
   /opt/at3.0/bin/gcc
   ```

   b. Build an MPI program using the mpicc compiler wrapper (now using IBM Advance Toolchain for PowerLinux) and run the `ldd` command on the resulting executable. Make sure that the `libc.so.6` library (and other libraries) resolve to libraries in the `/opt/at3.0/lib64` directory hierarchy:

   ```
   Note:
   $ mpicc -o hello_c hello_c.c
   $ ldd hello_c
   ldd hello_c
   linux-vdso64.so.1 => (0x0000000000000000)
   libmp.so.0 => /usr/local/openmpi-1.4.2-tm/lib/libmp.so.0 (0x0000000000000000)
   libopen-rte.so.0 => /usr/local/openmpi-1.4.2-tm/lib/libopen-rte.so.0 (0x0000000000140000)
   libopen-pal.so.0 => /usr/local/openmpi-1.4.2-tm/lib/libopen-pal.so.0 (0x00000000001c0000)
   libdl.so.2 => /opt/at3.0/lib64/libdl.so.2 (0x0000000000250000)
   libns1.so.1 => /opt/at3.0/lib64/libns1.so.1 (0x0000000000270000)
   libutil.so.1 => /opt/at3.0/lib64/libutil.so.1 (0x00000000002a0000)
   libm.so.6 => /opt/at3.0/lib64/power6/libm.so.6 (0x00000000002c0000)
   ```

Chapter 6. Building specialized versions of Open MPI  37
Related concepts:

Chapter 1, "Scope, requirements, and support," on page 1

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.

**Configuring Open MPI for use with IBM XL compilers**

Put your short description here; used for first paragraph and abstract.

**Before you begin**

Ensure that Open MPI and the IBM XL Compiler RPMs are installed on the system.

**About this task**

This procedure will enable the use of Open MPI to build and run HPC applications with the IBM XL compilers. The use of the XL compilers can provide significant performance improvements over the distro-supplied compilers.

This procedure does not require that Open MPI be reconfigured or rebuilt. It relies solely on enhancing the Open MPI implementation to be knowledgeable of the XL compilers, therefore it can be done for either Open MPI build (the rpm installed version or the version integrated with torque).

The procedure given below is specifically for the xlc compiler. However, the same procedure can be followed to enable all of the languages and variants supported by the XL compilers to be used with Open MPI.

On all nodes, as the root user, follow the procedures below.

**Procedure**

1. To create a wrapper compiler to integrate the use of xlc with Open MPI, complete the following steps:
   a. Run the following command:
      ```bash
      # ompi_install_dir=/usr/local/openmpi-1.4.2-tm/
      ```
   b. In the Open MPI binary directory, symbolically link opal_wrapper to the desired wrapper compiler name (in this case, mpixlc):
      ```bash
      # ln -s ${ompi_install_dir}/bin/opal_wrapper ${ompi_install_dir}/bin/mpixlc
      ```
   c. In the Open MPI share/openmpi directory, copy the mpicc-wrapper-data.txt file to the mpixlc-wrapper-data.txt file:
      ```bash
      # cd ${ompi_install_dir}/share/openmpi
      # cp mpicc-wrapper-data.txt mpixlc-wrapper-data.txt
      ```
   d. Edit the mpixlc-wrapper.txt file as shown in the following example:
      ```bash
      # diff mpicc-wrapper-data.txt mpixlc-wrapper-data.txt
      14c14
      < compiler=gcc
      ---
      > compiler=xlc
      ```
      ```bash
      17,18c17,18
      < compiler_flags=-pthread -m64
      ---
      > compiler_flags=-qthreaded -q64
      ```
      ```bash
      38
      ```
Once this is done, you should be able to build your applications with mpixlc and it will use the IBM xlc compiler.

2. To create a wrapper compiler to integrate the use of xlf with Open MPI, complete the following steps:
   a. Run the following command:
      ```
      # ompi_install_dir=/usr/local/openmpi-1.4.2-tm/
      
      # ln -s ${ompi_install_dir}/bin/opal_wrapper ${ompi_install_dir}/bin/mpixlf
      
      # cd ${ompi_install_dir}/share/openmpi
      # cp mpif77-wrapper-data.txt mpixlf-wrapper-data.txt
      ```
   b. In the Open MPI binary directory, symbolically link opal_wrapper to the desired wrapper compiler name (in this case, mpixlf):
      ```
      # ln -s ${ompi_install_dir}/bin/opal_wrapper ${ompi_install_dir}/bin/mpixlf
      ```
   c. In the Open MPI share/openmpi directory, copy the mpif77-wrapper-data.txt file to the mpixlf-wrapper-data.txt file.
      ```
      # cd ${ompi_install_dir}/share/openmpi
      # cp mpif77-wrapper-data.txt mpixlf-wrapper-data.txt
      ```
   d. Edit the mpixlf-wrapper.txt file as shown in the following example:
      ```
      # diff mpif77-wrapper-data.txt mpixlf-wrapper-data.txt
      14c14
      < compiler=gfortran
      ---
      > compiler=xlf
      17,18c17,18
      < compiler_flags=-pthread -m64
      < linker_flags=-m64
      ---
      > compiler_flags=-qthreaded -q64
      > linker_flags=-q64
      ```

   Once this is done, you should be able to build your applications with mpixlf and it will use the IBM xlf compiler.

3. To verify the compiler options that are being used, run the compiler with the --showme option (this step can be done as hpc user):
   ```
   $ mpixlc --showme
   xlc -I/usr/local/openmpi-1.4.2/include -qthreaded -q64 -q64 -L/usr/local/openmpi-1.4.2/lib -lmpi -lopenrte -lopen-pal -ldl -Wl,--export-dynamic -lnsl -lutil -lm -ldl
   ```

   ```
   $ mpixlf --showme
   xlf -I/opt/openmpi/1.4.2/include -qthreaded -q64 -q64 -L/opt/openmpi/1.4.2/lib -lmpi_f77 -lmpi -lopen-rte -lopen-pal -ldl -Wl,--export-dynamic -lnsl -lutil -lm -ldl
   ```

**Results**

If -I/usr/local/${ompi_install_dir}/include and -L/usr/local/${ompi_install_dir}/lib are shown in the output, then you have successfully configured Open MPI to build and run HPC application with IBM XL compilers. Note that the other wrapper compilers for mpif77, mpf90, mpic++, and the _r variants can be handled similarly.

**Related concepts:**

Chapter 1, “Scope, requirements, and support,” on page 1

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.

**Using Open MPI with huge pages**

If you have libhugetlbfs installed, you can choose to use 16MB huge pages with Open MPI when you start a distributed program.
Before you begin

Ensure that Open MPI is installed and that libhugetlbfs is installed.

About this task

The standard Open MPI configuration includes support for optimal use of RDMA-based communications, such as InfiniBand. This requires the use of special memory management routines within the Open MPI library to manage pages used in RDMA transfers. However, this is incompatible with the use of an interposer memory management library, such as libhugetlbfs.

To enable use of libhugetlbfs with Open MPI, the IBM Installation Toolkit contains a version of Open MPI which does not use the embedded Open MPI memory manager. After Open MPI is installed from the IBM Installation Toolkit, and you have your environment setup to use it, you can use libhugetlbfs as an interposer library with the LD_PRELOAD mechanism. This enables existing software to take advantage of libhugetlbfs without recompiling or relinking.

Procedure

1. To make use of 16MB huge pages, start the distributed application with the environment variable LD_PRELOAD set to libhugetlbfs.so and HUGETLB_MORECORE set to yes. The following example shows how the hpc user can start an application with these settings:

   $ mpirun -x LD_PRELOAD=libhugetlbfs.so -x HUGETLB_MORECORE=yes 
   -x OMP\_MCA\_memory\_ptmalloc2\_disable=1 -np <#> <program>

   Note: In this example, the -x flag of the mpirun command tells mpirun to propagate the designated environment setting to all of the processes of the distributed job.

2. Verify that huge pages are used by the application.

   You can verify the use of libhugetlbfs by running a job which does dynamic memory allocation and then observing the values of HugePages_Total and HugePages_Free in /proc/meminfo. If the job uses huge pages, when the application runs, the value of HugePages_Free decreases from the value it shows before you run the program.

   a. Check the values of HugePages_Total and HugePages_Free before you run the program, as shown in the following example:

      # egrep 'HugePages_(Total|Free)' /proc/meminfo
      HugePages_Total:  400
      HugePages_Free:  400

   b. Check the values of HugePages_Total and HugePages_Free while the program is running, as shown in the following example:

      # egrep 'HugePages_(Total|Free)' /proc/meminfo
      HugePages_Total:  400
      HugePages_Free:  80

3. Check the values of HugePages_Total and HugePages_Free when the program is has completed, as shown in the following example:

   # egrep 'HugePages_(Total|Free)' /proc/meminfo
   HugePages_Total:  400
   HugePages_Free:  400

Related concepts:

Chapter 1, “Scope, requirements, and support,” on page 1

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.
Chapter 7. Testing the InfiniBand interconnect performance with Intel MPI Benchmark

Validate the InfiniBand interconnect using a commonly used benchmark called Intel MPI Benchmark (IMB).

This section focuses on verifying the performance of the InfiniBand interconnects. This is an important step in verifying the performance of your cluster because if the interconnects cannot perform well, they can become a bottleneck for multi-node runs. You can complete the steps in each of the following sections as the hpc user.

Related concepts:
Chapter 1, “Scope, requirements, and support,” on page 1
This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.

Building IMB

IMB can be run on a single node, but for the purposes of testing InfiniBand performance, you will want to use at least two nodes for the test so that the messages will be passed across the InfiniBand link and not just within the shared memory of a single system.

About this task

Perform the following procedure on all of the nodes.

Procedure

2. Untar the package and change directory into the /src directory with the following commands:
   ```bash
tar zxfv IMB_3.2.tgz -C /home/hpc
cd /home/hpc/imb/src/
```
3. Edit the make_ict makefile to change the assignment of the CC value from mpiic to mpicc as shown:
   ```bash
LIB_PATH =
LIBS =
CC = mpicc
ifeq (,$(shell which $(CC)))
$(error $(CC) is not defined through the PATH <clipped>)
endif
OPTFLAGS =
CLINKER = $(CC)
LDFLAGS =
CPPFLAGS =

export CC LIB_PATH LIBS OPTFLAGS CLINKER LDFLAGS CPPFLAGS
include Makefile.base
```
4. Run the make command. When the make command completes, the IMB-MPI1 executable is shown with other object files and executables.
Running IMB

You can run IBM to determine whether you need to affinitize the processes to increase performance.

Procedure

1. Run IMB_MPI1 pingpong from management node:

   ```
   $ cd /home/hpc
   $ mpirun -np 2 -host compute_node1,compute_node2 imb/src/IMB-MPI1 pingpong
   ```

   Verify that you see the IMB output on your screen.

2. Run IMB in a pbs job with the following steps. This example job runs three IMB-MPI1 workloads: pingpong, sendrecv, and exchange across two nodes.

   ```
   Note: Perform this step for every InfiniBand link.
   ```

   a. Create the job.pbs file as shown:

   ```
   #PBS -N imb_2node
   #PBS -q batch
   #PBS -l nodes=2,pmem=100m,walltime=00:30:00
   #PBS -M admin@example.com
   #PBS -m e
   #PBS -V
   
   cd /home/hpc
   mpirun -np 2 --host compute_node1,compute_node2 imb/src/IBM-MPI1 pingpong
   ```

3. Submit the job with the `qsub` command, as shown in the following example:

   ```
   $ qsub job.pbs
   3.mgmt_node.example.com
   ```

Results

Two new output files are available after running the job: one containing job outputs and another containing any errors. They are named `<job name>.o<job identifier>` and `<job name>.e<job identifier>`, respectively. These output files are located on the compute node where the job ran.

The following output is the `imb_2node.o3` file for the job that ran in the test environment, including the output of expected performance for the pingpong, sendrecv, and exchange workloads on a single InfiniBand link:

```
#---------------------------------------------------
# Intel (R) MPI Benchmark Suite V3.2, MPI-1 part
#---------------------------------------------------
# Machine : ppc64
# System : Linux
# Release : 2.6.32.12-0.7-ppc64
# Version : #1 SMP 2010-05-20 11:14:20 +0200
# MPI Version : 2.1
# MPI Thread Environment: MPI_THREAD_SINGLE

# New default behavior from Version 3.2 on:
# the number of iterations per message size is cut down
```
# dynamically when a certain run time (per message size sample)
# is expected to be exceeded. Time limit is defined by variable
# "SECS_PER_SAMPLE" (=> IMB_settings.h)
# or through the flag => -time

# Calling sequence was:

# IMB-MPI1 pingpong sendrecv exchange

# Minimum message length in bytes: 0
# Maximum message length in bytes: 4194304

# MPI_Datatype : MPI_BYTE
# MPI_Datatype for reductions : MPI_FLOAT
# MPI_Op : MPI_SUM

#
# List of Benchmarks to run:

# PingPong
# Sendrecv
# Exchange

#Benchmarking PingPong
# #processes = 2
#------------------------------------------
#bytes #repetitions t[usec] Mbytes/sec
# 0    1000 3.42 0.00
# 1    1000 3.61 0.26
# 2    1000 3.63 0.53
# 4    1000 3.58 1.06
# 8    1000 3.37 2.26
# 16   1000 3.28 4.65
# 32   1000 3.33 9.15
# 64   1000 3.37 18.11
# 128  1000 3.51 34.75
# 256  1000 3.86 63.23
# 512  1000 4.54 107.44
# 1024 1000 5.83 167.51
# 2048 1000 7.93 246.42
# 4096 1000 12.39 315.15
# 8192 1000 16.83 464.20
# 16384 1000 18.94 825.08
# 32768 1000 27.44 1138.76
# 65536 1000 44.30 1410.69
# 131072 1000 78.01 1602.41
# 262144 1000 145.32 1720.40
# 524288 1000 280.61 1781.86
# 1048576 1000 549.60 1819.50
# 2097152 1000 1088.37 1837.60
# 4194304 1000 2162.96 1849.32

#Benchmarking Sendrecv
# #processes = 2
#------------------------------------------
#bytes #repetitions t_min[usec] t_max[usec] t_avg[usec] Mbytes/sec
# 0    1000 3.23 3.23 3.23 0.00
# 1    1000 3.33 3.33 3.33 0.57
# 2    1000 3.39 3.39 3.39 1.13
# 4    1000 3.33 3.33 3.33 2.29
# 8    1000 3.34 3.35 3.34 4.56
# 16   1000 3.37 3.38 3.37 9.04

Chapter 7. Testing the InfiniBand interconnect performance with Intel MPI Benchmark
## Benchmarking Exchange

Related concepts:

Chapter 1, “Scope, requirements, and support,” on page 1

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.
Chapter 8. Related information

You can find additional information about the processes and tools described in these procedures.

IBM Installation
Toolkit for PowerLinux

Open MPI
http://www.open-mpi.org/

IBM Advance
Toolchain for PowerLinux
ftp://linuxpatch.ncsa.uiuc.edu/toolchain

TORQUE Resource Manager
http://www.clusterresources.com/torquedocs21/

Maui Cluster Scheduler

IBM XL C/C++ and XL Fortran Compilers
http://www.ibm.com/software/awdtools/xlc++/linux/

libhugetlbfs
http://sourceforge.net/projects/libhugetlbfs/

ATLAS math libraries
http://sourceforge.net/projects/math-atlas/

Related concepts:
Chapter 1, “Scope, requirements, and support,” on page 1

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.
Chapter 9. Setting up an HPC cluster with Red Hat Enterprise Linux

You can set up and manage a cluster of compute nodes using common open-source based cluster and resource management tools on POWER-based systems running Red Hat Enterprise Linux 5.5. This demonstration has examples of how to use the Open MPI, Torque, and Maui open source software to define and manage a small set of compute servers interconnected with InfiniBand in a classic High Performance Computing (HPC) cluster.

Key tools and technologies detailed in this demonstration include ATLAS, TORQUE, Maui, and Open MPI.

Scope, requirements, and support

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.

Systems to which this information applies

PowerLinux (POWER6 and later)

Intended audience

This blueprint is intended for advanced Linux system administrators and programmers who are already familiar with basic HPC concepts, terminology, products, including InfiniBand interconnects. The instructions assume that you have a general understanding of the usage requirements for connecting nodes with InfiniBand and with MPI-based applications.

Scope and purpose

This document is based in part on the collaborative experiences of the IBM Linux Technology Center, IBM’s systems development teams, and Rice University in deploying and managing the POWER7-based BlueBioU cluster, at [http://bluebiou.rice.edu/](http://bluebiou.rice.edu/)

This document discusses the following software that you can use to deploy a simple cluster with POWER-based systems:
- Basic InfiniBand setup
- Open MPI
- Torque
- IBM Advance Toolchain for PowerLinux
- libhugetlbfs

The following topics are not covered:
- Advanced cluster management products, such as:
  - Moab (Cluster Resources)
  - IBM Parallel Environment
  - Extreme Cloud Administration Toolkit (xCAT)
- Detailed problem determination
- In-depth technology discussion

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Resources for in-depth discussion of these and other topics are listed in Related Information.

Test environment

The instructions in this blueprint were tested on IBM Power 575 systems with POWER6 processors running Red Hat Enterprise Linux 5.5. The BlueBioU team at Rice University has deployed a similar software stack with POWER7-based IBM Power 750 systems.

Hardware, software, and other prerequisites

In testing, one server was used as a “management node” and two other servers were the “compute nodes”. Each server had an InfiniBand adapter supporting physical connections to a shared InfiniBand switch.

The examples in this demonstration are focused on eHCA with a single port.

The following software resources are used to perform the steps in this blueprint:

- A Red Hat Enterprise Linux 5.5 YUM repository
- Torque Resource Manager software from [http://www.clusterresources.com/torquedocs21/1.1/installation.shtml](http://www.clusterresources.com/torquedocs21/1.1/installation.shtml)

This blueprint focuses on Red Hat Enterprise Linux 5.5, but you can apply the concepts easily to other Linux distributions that are supported on POWER-based systems.

The Red Hat createrepo RPM package must be installed on all nodes of the cluster.

The Red Hat Enterprise Linux 5.5 YUM repository must be available on each of the nodes.

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IBM Services

Linux offers flexibility, options, and competitive total cost of ownership with a world class enterprise operating system. Community innovation integrates leading-edge technologies and best practices into Linux.

IBM is a leader in the Linux community with over 600 developers in the IBM Linux Technology Center working on over 100 open source projects in the community. IBM supports Linux on all IBM servers, storage, and middleware, offering the broadest flexibility to match your business needs.
Open source-based HPC compute cluster on POWER

You can learn about basic concepts of HPC clusters, and get a brief overview of some of the open source software you can use to build an HPC cluster on POWER processor-based systems.

HPC compute clusters

This blueprint is focused on the class of servers which are used primarily for compute-intensive work like computational simulations of weather, bioinformatics, and so on. In this class of compute-intensive workloads, a single compute job may execute on multiple servers simultaneously and often requires extensive communication between each of the servers. In these server clusters, the servers typically share a dedicated high-speed network (often based on InfiniBand), are densely and closely located relative to each other, and are homogeneous.

Management node

A management node, typically a separate server, is used for running the cluster’s scheduler and resource managers. This blueprint shows how to install a Maui Cluster Scheduler and the Torque Resource Manager which collectively manage and control the compute nodes.

Compute node

With a large number of compute nodes, there is usually a requirement for schedulers and server resource managers to prioritize and manage which jobs can be executed on the cluster. In this blueprint, we focus on just a handful of compute nodes, with the notion that the compute node setup is a repeatable incremental process. As you need to increase the number of compute nodes in your cluster, you can refer to these examples to ensure that the additional nodes are properly prepared.

InfiniBand interconnect

The example cluster in this blueprint uses InfiniBand to connect the nodes of the cluster. InfiniBand is a scalable, low-latency, high performance communication mechanism frequently used in HPC environments.
The software components

These are the essential components of the HPC software stack, including compilers, math libraries, communication stack, cluster management and scheduling software, and software used for installation of key software components for POWER processor-based systems.

IBM Installation Toolkit for PowerLinux

The IBM Installation Toolkit for PowerLinux provides a set of tools that simplifies the installation of IBM value-added software necessary to fully use the capabilities of the Power platform. In particular, for this cluster we are interested in the two 64-bit Open MPI packages included in the IBM Installation Toolkit Version 4.1.

InfiniBand software stack

The InfiniBand software stack provides cluster-knowledgeable middleware, such as MPI libraries, access to the low-latency, high bandwidth InfiniBand fabric for cluster communications. Red Hat Enterprise Linux provides an InfiniBand software stack.

Open MPI

The Open MPI project provides an open source implementation of the MPI-2 standard. It is developed and maintained by a consortium of academic, research, and industry partners. Open MPI is therefore able to combine the expertise, technologies, and resources from across the High Performance Computing community in order to build reliable and high performance MPI library.

IBM Advance Toolchain for PowerLinux

The IBM Advance Toolchain for PowerLinux is a collection of free software application development products specifically tailored to make use of IBM POWER processor features. The package includes GCC (GNU Compiler Collection), GLIBC (GNU C Libraries), GNU binary utilities, GDB ( GNU debugger), and the performance analysis tools (QProfile and Valgrind) in a self contained Toolchain. The IBM Advance Toolchain for PowerLinux duplicates the function of packages already delivered by Linux distributors but provides additional features for the POWER6 and POWER7 processors as indicated in the IBM Advance Toolchain for PowerLinux Release Notes ’Features’ section. The IBM Advance Toolchain for PowerLinux is built and distributed by the University of Illinois.

TORQUE resource manager

Tera-scale Open-source Resource and QUEue Manager (TORQUE) is a workload and resource-management system that manages batch jobs and compute nodes and schedules the execution of those jobs. The TORQUE system includes three pieces: the server, the scheduler, and the job executor. The server process, called pbs_server, creates and manages jobs and queues and dispatches jobs for execution to compute nodes, where the job executor, called pbs_mom, starts the job.

Maui Cluster Scheduler

The Maui Cluster Scheduler is a policy engine used to improve the manageability and efficiency of various sized clusters, from small clusters with just a few processors to very large supercomputers. The Maui Cluster Scheduler is intended to support a large array of scheduling policies, dynamic priorities, extensive reservations, and fairshare.

IBM XL C/C++ and XL Fortran compilers

XL C/C++ for Linux V11.1 is a highly advanced optimizing compiler for the selected Linux distributions. The compiler runs on IBM Power Systems and is an industry standards-based professional programming
tool that can be used for developing large, complex, computationally intensive 32-bit and 64-bit applications in the C and C++ programming languages.

XL Fortran is a standards-based Fortran compiler with extensive features to help you create high performance applications. A highly advanced optimizing compiler for the Linux operating system, runs on IBM Power Systems.

**libhugetlbfs**

The libhugetlbfs library interacts with the Linux hugetlbfs to make large pages available to applications in a transparent manner. On POWER processor-based systems, this library provides applications easy access to the 16 MB huge pages.

**ATLAS math libraries**

Automatically Tuned Linear Algebra Software (ATLAS) provides highly optimized Linear Algebra kernels for arbitrary cache-based architectures. ATLAS provides ANSI C and Fortran77 interfaces for the entire BLAS API, and a small portion of the LAPACK AP.

**Related concepts:**

[Chapter 1, “Scope, requirements, and support,” on page 1](#)

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.

**Setting up the cluster**

You can see an overview of the cluster component setup for this example, including whether components are set up on the management node or compute nodes, and which user does the installation or configuration tasks.

The cluster is dependent on each of the compute nodes being connected with InfiniBand. Although it is common that all nodes have an InfiniBand connection, it is not required for the the management node. However, the InfiniBand packages should still be installed on the management node so that other package builds can use the InfiniBand components. Therefore, we start by installing the latest Open MPI and InfiniBand packages on all nodes - the management node and all compute nodes.

The installation and configuration tasks are performed by the root user except where noted in the following tables.

**Table 3. Cluster setup tasks**

<table>
<thead>
<tr>
<th>Task</th>
<th>Management node</th>
<th>Compute node</th>
</tr>
</thead>
<tbody>
<tr>
<td>Installing OpenMPI and InfiniBand packages</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>Configuring InfiniBand</td>
<td>Not required</td>
<td>Yes</td>
</tr>
<tr>
<td>Installing Torque Resource Manager</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>Installing Maui Cluster Scheduler</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>Configuring Torque</td>
<td>Yes</td>
<td>Yes</td>
</tr>
</tbody>
</table>

**Table 4. Advanced software setup tasks**

<table>
<thead>
<tr>
<th>Task</th>
<th>Management node</th>
<th>Compute node</th>
</tr>
</thead>
<tbody>
<tr>
<td>Advanced software setup</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
### Table 4. Advanced software setup tasks (continued)

<table>
<thead>
<tr>
<th>Advanced software setup</th>
<th>Yes</th>
<th>Yes</th>
</tr>
</thead>
<tbody>
<tr>
<td>Installing libhugetlbfs</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>Installing IBM Advance Toolchain for PowerLinux</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>Installing the IBM XL C/C++ and Fortran compilers</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>Installing ATLAS math libraries</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>Building Open MPI with Torque</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>Configuring Open MPI for use with the Advance Toolchain</td>
<td>Yes, as hpc user</td>
<td>Yes, as hpc user</td>
</tr>
<tr>
<td>Configuring Open MPI for use with the IBM XL compilers</td>
<td>Yes, as root when installing and then as hpc user when verifying</td>
<td>Yes, as root when installing and then as hpc user when verifying</td>
</tr>
<tr>
<td>Using Open MPI with huge pages</td>
<td>Yes, as hpc user</td>
<td>Yes, as hpc user</td>
</tr>
<tr>
<td>Testing the InfiniBand interconnect performance with Intel MPI Benchmark (IMB)</td>
<td>Yes, as hpc user when installing and submitting jobs</td>
<td>Yes, as hpc user when installing</td>
</tr>
</tbody>
</table>

**Related concepts:**

[Chapter 1, “Scope, requirements, and support,” on page 1](#)

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.

### Setting up the hpc user

The hpc user configures and uses various optional software components on the cluster, including Open MPI, the IBM XL compilers, and the Intel MPI Benchmark (IMB).

### About this task

You must ensure that the hpc user exists on all the nodes of the cluster in order to perform some of the configuration and testing tasks described in this blueprint.

The hpc user needs password-less connectivity among all the nodes in order to enable Open MPI applications to pass messages between nodes. Without password-less connectivity, you would be required to enter the password for each node whenever a job was run. The stage needs to be set just so.

### Procedure

1. Create the hpc user on any nodes where it does not already exist. If the hpc user does not exist on a node, you can create the hpc user with the following commands:

   ```
   # useradd -m hpc
   # passwd hpc
   ```

2. Set up password-less connectivity for the hpc user among all the nodes in the cluster:

   On the management node and all compute nodes, check if hpc user has password-less connectivity. You must be able to use ssh to connect to and from all the nodes without a password request. (There are several methods available to set up password-less connectivity, outside the scope of this document.)

   When you have successfully configured ssh for the hpc user, you will be able to use ssh to connect between any two nodes in the cluster without a password. The following example shows a password-less ssh connection from the host named compute_node1 to the host named compute_node2:
Installing Open MPI and InfiniBand packages

You can obtain and use the IBM Installation Toolkit for PowerLinux to install the Open MPI and InfiniBand software packages.

Before you begin

1. Ensure that the createrepo RPM package is installed on each node of the cluster.

   Note:
   - You must register and sign in before you can download the software.
   - As of the time of writing of this blueprint, the current IBM Installation Toolkit version is 4.1.

About this task

In these examples we assume the operating system (Red Hat Enterprise Linux 5.5) has already been installed on all of the servers – in this case the management node and the two compute nodes.

Note: The IBM Installation Toolkit can be used to install the Linux distribution for servers as well, but installing the operating system is outside the scope of this discussion.

The root user performs all the steps of this procedure.

Perform these steps for each node of the cluster:

Procedure

1. Create a local IBM Installation Toolkit YUM repository:

   a. Mount the IBM Installation Toolkit ISO media and copy the Red Hat directory with all of the Red Hat-related RPM packages to a directory of your choice. The following example uses /opt/ibmit41 as the destination directory:

      # mkdir /mnt/ibmtoolkit
      # mkdir /opt/ibmit41
      # mount -o loop -t iso9660 IBM_Installation_Toolkit_41.iso /mnt/ibmtoolkit
      # cp -arL /mnt/ibmtoolkit/* /opt/ibmit41
      # umount /mnt/ibmtoolkit
      # rmdir /mnt/ibmtoolkit

      Note: This example, uses the cp command’s -L flag order to dereference and copy files that are symbolic links in the /RedHat directory on the IBM Installation Toolkit ISO image.

   b. Use the createrepo command to create the repository, as in the following example:
# createrepo /opt/ibmit41/RedHat
33/33 - RPMS/xconfig-0.1-1.ppc.rpm
Saving Primary metadata
Saving file lists metadata
Saving other metadata

c. Create the definition file for this new repository.
The /etc/yum.repos.d directory is the default YUM repository location. Therefore, in this example, the definition file is created as /etc/yum.repos.d/ibmit41.repo. The content of the definition file should look like the following example.

Note: The baseurl parameter is set to point to the local directory where the createrepo command was issued against in the previous step and where the Red Hat RPM packages reside.

```
[ibmit41]
name=ibmit41
baseurl=file:///opt/ibmit41/RedHat
enabled=1
gpgcheck=0
```
d. Verify that the local repository is set up correctly, as in the following example:

```
# yum repolist
Loaded plugins: rhnplugin, security
This system is not registered with RHN.
RHN support will be disabled.
repo id repo name status
core-0 core-0 enabled: 32
core-1 core-1 enabled: 33
core-2 core-2 enabled: 3,089
ibmit41 ibmit41 enabled: 33
repolist: 3,187
```

2. Install the Open MPI and InfiniBand-related packages from the local IBM Installation Toolkit YUM repository and the Red Hat Enterprise Linux 5.5 YUM repository.

```
# yum install sysstat openmpi-1.4.2-1.ppc64 openib mpi-selector infiniband-diags perftest ofed-docs libibverbs* librdmacm* libehca*
```

Note:
- "sysstat" is a package for extended performance tools on a Power system.
- The Open MPI package is provided on the IBM Installation Toolkit. This is a newer package of Open MPI built for 64-bit applications which has been packaged and provided for customers.
- The remainder of the packages are standard packages necessary for MPI applications using InfiniBand connectivity.
- "ofed" is from the OpenFabrics Alliance – [https://www.openfabrics.org/index.php](https://www.openfabrics.org/index.php). The OpenFabrics Enterprise Distribution (OFED) is a standardized set of enabling software generally targeted at high-performance low-latency computing.

3. Configure the PATH and LD_LIBRARY_PATH environment variables for the hpc user to include the paths for Open MPI and software installed in /usr/local/sbin for this HPC cluster configuration by modifying the /home/hpc/.bashrc file as follows:

a. Add the /usr/local/sbin directory and the /opt/openmpi/1.4.2/bin directory to the beginning of the PATH environment variable.

```
a. Add the /usr/local/sbin directory and the /opt/openmpi/1.4.2/bin directory to the beginning of the PATH environment variable.
```

b. Add the /opt/openmpi/1.4.2/lib directory to the beginning of the LD_LIBRARY_PATH environment variable.

```
b. Add the /opt/openmpi/1.4.2/lib directory to the beginning of the LD_LIBRARY_PATH environment variable.
```

The following example shows a simple method to append these modifications to the environment variables in the .bashrc file for the hpc user:
cat >> /home/hpc/.bashrc <<EOF
export PATH=/usr/local/sbin:/opt/ompi/1.4.2/bin:$PATH
export LD_LIBRARY_PATH=/opt/ompi/1.4.2/lib:$LD_LIBRARY_PATH
EOF

Results

After you have completed this installation process on each node of the cluster, every system will have the required Open MPI and InfiniBand software installed.

What to do next

You are now ready to configure and validate the InfiniBand connectivity between all the InfiniBand-connected nodes.

Related concepts:

Chapter 1, “Scope, requirements, and support,” on page 1

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.

Configuring InfiniBand

You can learn about the steps needed to configure and confirm InfiniBand connectivity.

Before you begin

The Open MPI and InfiniBand packages must already be installed on all nodes.

The allowable amount of locked (pinned) memory needs to be set to unlimited. To do this, edit /etc/security/limits.conf and add the following lines:

```bash
#<domain> <type> <item> <value>
#
* soft memlock unlimited
* hard memlock unlimited
```

About this task

These steps assume your servers have InfiniBand adapters installed and are connected to an InfiniBand switch. In this example, all nodes are assumed to be connected to the same InfiniBand fabric.

This procedure is required for all nodes that will have InfiniBand traffic.

Note: You will only perform this process on the management node if the management node has an InfiniBand connection. The root user performs all the steps of this procedure.

Procedure

1. Specify the `nr_ports` and `port_act_time` options for the IBM InfiniBand eHCA kernel module, `ib_ehca`, by creating the `/etc/modprobe.d/ib_ehca.conf` file containing the following line:

   ```bash
   options ib_ehca nr_ports=-1 port_act_time=120
   ```

   Note:
   - The `nr_ports` option is set to -1. This causes the module to autodetect the number of active ports.
   - `port_act_time` option is set to 120. This causes the module to wait for 120 seconds for port activation.
2. Edit `/etc/ofed/openib.conf` and change the values of `SDP_LOAD`, `RDS_LOAD`, `SRP_LOAD`, and `ISER_LOAD` to `no`. This changes the default setting to load only the drivers that are needed for this setup. The resulting file will be similar to the following example:

```
# Load IPoIB
IPOIB_LOAD=yes
# Load SDP module
SDP_LOAD=no
# Load the RDS protocol driver
RDS_LOAD=no
# Load SRP module
SRP_LOAD=no
# Load iSER module
ISER_LOAD=no
```

3. Configure the openibd service:

   a. Run `chkconfig` to configure the `openibd` service to start automatically whenever the operating system starts, as shown in the following example:

   ```
   # chkconfig openibd on
   # chkconfig --list openibd
   openibd 0:off 1:off 2:on 3:on 4:on 5:on 6:off
   
   Note: The output from `chkconfig --list openibd` in this example shows whether the `openibd` service will start for each runlevel.
   
   b. Run the `kudzu` command to detect the InfiniBand hardware.

   Note: The `/etc/sysconfig/hwconf` file will also be created which is referenced by the openibd service.

   c. Start the openibd service as shown in the following example:

   ```
   # service openibd start
   Loading OpenIB kernel modules: [ OK ]
   ```

4. Validate InfiniBand device configuration by displaying InfiniBand devices on the node:

   a. To list InfiniBand devices on the node, run the `ibv_devices` command. This step validates that the previous steps have been completed and the InfiniBand adapters are correctly detected. If your InfiniBand devices are correctly configured, the output of the `ibv_devices` command will look similar to the following example:

   ```
   # ibv_devices
   device node GUID
   ------- ----------------
   ehca0 0002550010e56a00
   ehca1 0002550010e56c00
   ```

   b. Use `ibv_devinfo` to query the InfiniBand devices. Verify that the port status is active and that `sm_lid` is not 0 for all connected ports. The following example shows typical output from the `ibv_devinfo` command:

   ```
   # ibv_devinfo
   hca_id: ehca0
   node_guid: 0002:5500:7018:9600
   sys_image_guid: 0000:0000:0000:0000
   vendor_id: 0x5076
   vendor_part_id: 1
   hw_ver: 0x2000021
   phys_port_cnt: 2
   port: 1
   state: PORT_ACTIVE (4)
   max_mtu: 4096 (5)
   ```
active_mtu: 4096 (5)
sm_lid: 1
port_lid: 29
port_lmc: 0x00

port: 2
state: PORT_ACTIVE (4)

max_mtu: 4096 (5)
active_mtu: 4096 (5)
sm_lid: 1
port_lid: 41
port_lmc: 0x00

Related concepts:
Chapter 1, “Scope, requirements, and support,” on page 1

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.

Testing InfiniBand connectivity
This series of tests assures connectivity, reasonable bandwidth, and latency performance between a pair of InfiniBand-connected nodes.

Before you begin
Configure the InfiniBand devices on all nodes, as described in “Configuring InfiniBand” on page 12.

About this task
Test the connectivity for each node with at least one other node in the cluster before you continue setting up the cluster.

These tests run between two nodes, one node acting as the server and the other node acting as the client for purposes of the test. The server node initiates a listening server and waits to receive requests from the client. The client node sends the request to the specified server.

The root user performs all the steps of this procedure.

Procedure
1. Test InfiniBand connectivity with the ibv_rc_pingpong command:
   a. Run the ibv_rc_pingpong command on the server node, as shown in the following example:
      
      ```
      compute_node1 # ibv_rc_pingpong
      local address: LID 0x001e, QPN 0x000033, PSN 0x150335
      ```
   b. Run the ibv_rc_pingpong command on the client node with the hostname of the server node as the parameter. In the following example, the hostname of the server node is compute_node1:
      
      ```
      compute_node2 # ibv_rc_pingpong compute_node1
      local address: LID 0x001e, QPN 0x000075, PSN 0x1fa58b
      remote address: LID 0x001c, QPN 0x000033, PSN 0x150335
      8192000 bytes in 0.02 seconds = 3601.08 Mbit/sec
      1000 iters in 0.02 seconds = 18.20 usec/iter
      ```
   If the connection is successful, the ibv_rc_pingpong process on the server will produce output indicating the connection from the client, and then exit. The following example shows output on the server that results from a successful connection:

   ```
   remote address: LID 0x0016, QPN 0x000075, PSN 0x1fa58b
   8192000 bytes in 0.02 seconds = 3584.34 Mbit/sec
   1000 iters in 0.02 seconds = 18.28 usec/iter
   ```
2. Test the bidirectional InfiniBand bandwidth with the `rdma_bw` command:
   a. On the server node, run `rdma_bw -b` as shown in the following example:

   ```
   # rdma_bw -b
   #
   15151: | port=18515 | sb_port=1 | size=65536 | tx_depth=100 | sl=0 | iters=1000 |
   duplex=1 | cma=0 |
   15151: Local address: LID 0x12, QPN 0x4377, PSN 0x8b5218 RKey 0x679129 VAddr 0x00040000340000
   15151: Remote address: LID 0x11, QPN 0x447b, PSN 0x8b58f6, RKey 0xa81105 VAddr 0x000400001a0000
   Warning: measured timestamp frequency 511.951 differs from nominal 4704 MHz
   15151: Bandwidth peak (#0 to #786): 3410.28 MB/sec
   15151: Bandwidth average: 3408.49 MB/sec
   15151: Service Demand peak (#0 to #786): 146 cycles/KB
   15151: Service Demand Avg : 146 cycles/KB
   The important item to check in this output is the Bandwidth average: value. Throughput greater than 3000 MB/sec is desirable. A bandwidth average value of less than 3000 MB/sec may indicate a performance issue.
   ```

   **Note:** The output and warnings can be safely ignored for the purposes of this test.

3. Test bidirectional InfiniBand latency with the `rdma_lat` command:
   a. On the server node, run the `rdma_lat` command.

   ```
   # rdma_lat
   ```

   b. On the client node, run the `rdma_lat` command with hostname of the server as the parameter. The hostname of the listening server in the following example is `compute_node1`:

   ```
   # rdma_lat compute_node1
   local address: LID 0x12 QPN 0x43b2 PSN 0xb766cf RKey 0x67912e VAddr 0x00000010030001
   remote address: LID 0x11 QPN 0x46f6 PSN 0xaa5ce6 RKey 0xa8110b VAddr 0x00000010030001
   Warning: measured timestamp frequency 511.938 differs from nominal 4704 MHz
   Latency typical: 3.61665 usec
   Latency best : 3.22695 usec
   Latency worst : 28.9488 usec
   The important item to check in this output is the Latency typical: value. A Latency typical value of less than 4.0 usec is desirable.
   ```

   **Note:** The other output and warnings can be safely ignored.

**Related concepts:**

[Chapter 1, “Scope, requirements, and support,” on page 1](#)

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.

### Installing the Management Node

Install the TORQUE resource manager and the Maui Cluster Scheduler on the management node in order to control and track jobs on the compute nodes. Build special torque client and Machine Oriented Mini-server (MOM) packages to install on the compute nodes after you install the Torque and Maui software on the management node.
This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.

## Installing Torque resource manager

You install the TORQUE resource manager only on the management node. These instructions show how to obtain, build and install the newest version of the TORQUE software.

### Before you begin

- Verify that the InfiniBand configuration is complete for all nodes by completing the tests in "Testing InfiniBand connectivity" on page 14.
- Ensure that the hpc user and the /home/hpc directory is set up on all nodes as described in "Setting up the hpc user" on page 10.

### About this task

The root user on the management node performs all the steps of this procedure.

### Procedure

1. As root user on the management node, download the newest version of TORQUE resource manager from: [http://www.clusterresources.com/downloads/torque](http://www.clusterresources.com/downloads/torque)
   
   In this example, torque.2.4.8 is the latest available package.

2. Extract, configure, and build the torque software package in the /usr/local/src directory. The following example shows this process and the appropriate flags to use when you configure for the 64-bit Power Architecture:
   ```
   # tar zxf torque-2.4.8.tar.gz -C /usr/local
   # cd /usr/local/torque-2.4.8
   # ./configure --enable-docs --with-scp --enable-syslog CFLAGS=-m64 --libdir=/usr/local/lib64
   # make
   # make install
   # ldconfig
   ```

3. Initialize the torque server by running the setup script and indicating the root user:
   ```
   # ./torque.setup root
   initializing TORQUE (admin: root@compute_node1.example.com)
   Max open servers: 4
   Max open servers: 4
   ```

4. Verify that the /var/spool/torque/server_name file contains the fully qualified host name of the management node.

   **Note:**

   a. A short host name will also work if all the nodes in the cluster share the same name server. This should be created during the initialization step.

   b. The /var/spool/torque/server_name file was created by the `torque.setup` command.

   ```
   # cat /var/spool/torque/server_name
   mgmt_node.example.com
   ```

5. Build the Torque self-extracting packages for compute nodes. The following example shows the root user running make packages:
   ```
   # make packages
   ```

6. Copy the self-extracting packages you built for the compute nodes into the /home/hpc/comput-node-files directory, as shown in the following example:
Note: You must create the /home/hpc/compute-node-files directory if it doesn't already exist.

# mkdir /home/hpc/compute-node-files
# cp *.sh /home/hpc/compute-node-files/

7. Run the `libtool` command as shown in the following example to configure the libraries for the management node.

    # libtool --finish /usr/local/lib64

Results

You will use these packages in "Preparing the TORQUE packages for the compute nodes" on page 20.

Related concepts:

Chapter 1, "Scope, requirements, and support," on page 1

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.

Installing Maui cluster scheduler

The Maui server controls job scheduling across the cluster. These instructions show how to obtain, build, and install the newest version of the Maui cluster scheduler on the management node of the cluster.

Before you begin

Ensure that the TORQUE server is installed on the management node, as described in Installing the TORQUE resource manager.

About this task

The root user on the management node performs all the steps of this procedure.

Procedure

1. Download Maui from the following site: http://www.clusterresources.com/product/maui/

Note: you must register in order to download the software

For our example, we selected the Maui 3.3 version, the newest version as of the writing of this document.

2. Extract, configure, and build the Maui server software using the following commands:

    # tar -zxvf maui-3.3.tar.gz -C /usr/local/src
    # cd /usr/local/src/maui-3.3
    # chmod +x /usr/local/torque-2.4.8/pbs-config
    # ./configure --with-pbs=/usr/local CFLAGS=-m64 LDFLAGS=-m64
    # make
    # make install

3. Add the /usr/local/maui/bin directory to the PATH environment variable for the hpc user by appending the contents of the /usr/local/src/maui-3.3/etc/maui.sh file to the /home/hpc/.bashrc file.

    # cat /usr/local/src/maui-3.3/etc/maui.sh >> /home/hpc/.bashrc
    # cp /usr/local/src/maui-3.3/etc/maui.sh /home/hpc/compute-node-files/

4. Set up the Maui daemon as a service on the management node server:

    a. Edit the /usr/local/src/maui-3.3/etc/maui.d file and change the value of the MAUI_PREFIX variable to /usr/local/maui as shown in the following example:

        MAUI_PREFIX=/usr/local/maui
b. Copy the /usr/local/src/maui-3.3/etc/maui.d file to /etc/init.d/maui.d, as shown in the following example:

```
# cp /usr/local/src/maui-3.3/etc/maui.d /etc/init.d/maui.d
```

5. Edit the /usr/local/maui/maui.cfg file, which was created by the build process, to include the information needed for the environment of your hpc cluster:

a. Make sure the following lines are included as follows:

   SERVERPORT 42599
   ADMIN1 root hpc
   ADMIN3 ALL

b. Modify the SERVERHOST and ADMINHOST lines to contain the fully qualified host name for the management node. For example, if the fully qualified host name of your management node is mgmt_node.example.com, edit these lines as shown in the following example:

   SERVERHOST mgmt_node.example.com
   ADMINHOST mgmt_node.example.com

c. Verify that the RMCFG line contains the short host name in brackets, as shown in the following example:

   RMCFG[mgmt_node] TYPE=PBS

6. Create the /var/spool/torque/server_priv/nodes file to contain a list of all of the compute nodes in the cluster:

```
# cd /var/spool/torque/server_priv
# vi nodes
```

a. Use a text editor to add one line to the /var/spool/torque/server_priv/nodes file for each compute node in your cluster. Use the np parameter to define the number of CPU threads that are available for use on each node. For example, we have two compute nodes we are defining, each with 64 threads available:

   compute_node1.example.com np=64
   compute_node2.example.com np=64

b. Copy the /var/spool/torque/server_priv/nodes file to the /home/hpc/compute-node-files/ directory.

```
# cp /var/spool/torque/server_priv/nodes /home/hpc/compute-node-files
```

7. Set up Maui as a service on the management node using the chkconfig command, as shown in the following example:

```
# chkconfig --add maui.d
# chkconfig --level 3456 maui.d on
# chkconfig --list maui.d
maui.d 0:off 1:off 2:off 3:on 4:on 5:on 6:on
```

8. Start the Maui service on the management node as shown in the following example:

```
# service maui.d start
Starting MAUI Scheduler: [ OK ]
```

9. Set up the TORQUE server on the management node by copying the pbs_server file to the /etc/init.d/ directory, as shown in the following example:

```
# cd /usr/local/torque-2.4.8
# cp -p contrib/init.d/pbs_server /etc/init.d/
```

10. Add the pbs_server service to the management node with the chkconfig command, as shown in the following example:

    Note: The pbs_server service is the TORQUE resource manager service.

```
# chkconfig --add pbs_server
# chkconfig --level 3456 pbs_server on
# chkconfig --list pbs_server
pbs_server 0:off 1:off 2:off 3:on 4:on 5:on 6:on
```
11. Restart the pbs_server service on the management node in order to allow changes to take effect. The pbs_server service starts the batch server on the management node that will pick up any jobs. You can start the pbs_server service as shown in the following example:

```
# service pbs_server restart
Starting TORQUE Server: [ OK ]
```

Results

The TORQUE and Maui services are installed and running on the management node. You can query the TORQUE queue and server attributes with the `qmgr -c 'p s'` command.

Related concepts:

Chapter 1, “Scope, requirements, and support,” on page 1

Preparing the TORQUE packages for the compute nodes

You must create Torque Resource Manager installation packages for the compute nodes before you can configure the Machine Oriented Mini-server on the compute nodes.

Before you begin

Ensure that you have completed all of these prerequisite tasks:

- Build and install the Torque and Maui packages on the management node.
- Build the self-extracting installation packages and copy them to the `/home/hpc/compute-node-files` directory on the management node.
- Create the hpc user on the compute nodes as described in “Setting up the hpc user” on page 10.

About this task

The root user on the management node performs these steps.

Procedure

1. Create the `/usr/local/torque-2.4.8/mom_priv-config` file on the management node:

   **Note:** You will copy this temporary file to the `/home/hpc/compute-node-files` directory.

   a. Provide the following information in the `/usr/local/torque-2.4.8/mom_priv-config` file:

      - IP address of the pbsserver, (the same as the IP address of the management node)
      - IP address of the clienthost, (the same as the IP address of the management node)
      - Settings for important directories that are used by the Machine Oriented Mini-server

      The following example of the `mom_priv-config` file content shows how to format this information.

      **Note:** The IP address for your management node is specific to your environment. The rest of the file must be the same as this example if you have configured your hpc user as described in this document.

      ```
      $pbsserver    x.x.x.x # (IP address of management node)
      $clienthost   x.x.x.x # (IP address of management node)
      $usecp        */home/hpc /*home/hpc
      $usecp        */home /*home
      $usecp        */root /*root
      $usecp        */tmp_scratch /*tmp_scratch
      $tmpdir       /tmp
      ```

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b. Copy the `/usr/local/torque-2.4.8/mom_priv-config` file to the `/home/hpc/compute-node-files` directory.

2. Prepare for the configuration of the pbs_mom service on each compute node. The `pbs_mom` command starts a batch Machine Oriented Mini-server that will control job execution as directed by the TORQUE resource manager service, usage limits, and notifications.

   a. Update `/usr/local/torque-2.4.8/contrib/init.d/pbs_mom` file on the management node by adding `ulimit -l unlimited` as shown in the following example `pbs_mom` file:

   ```bash
   #!/bin/sh
   #
   # pbs_mom     This script will start and stop the PBS Mom
   #
   # chkconfig: 345 95 5
   # description: TORQUE/PBS is a versatile batch system for SMPs and clusters
   #
   ulimit -n 32768
   ulimit -l unlimited  # <--- add this line
   # Source the library functions
   . /etc/rc.d/init.d/functions
   ```

   b. Copy the `/usr/local/torque-2.4.8/contrib/init.d/pbs_mom` to the `/home/hpc/compute-node-files` directory.

   c. Use the `cp -p` command to preserve mode and ownership of the file as shown in the following example:

   ```bash
   # cp -p contrib/init.d/pbs_mom /home/hpc/compute-node-files/
   ```

3. Copy the `/home/hpc/compute-node-files` directory as an archive file from the management node onto each of the compute nodes:

   a. Create a tar archive of the contents of the `/home/hpc/compute-node-files` directory, as shown in the following example:

   ```bash
   # cd /home/hpc
   # tar zcvf compute-node-files.tar.gz compute-node-files
   compute-node-files/
   compute-node-files/torque-package-clients-linux-powerpc64.sh
   compute-node-files/torque-package-devel-linux-powerpc64.sh
   compute-node-files/torque-package-doc-linux-powerpc64.sh
   compute-node-files/torque-package-mom-linux-powerpc64.sh
   compute-node-files/torque-package-server-linux-powerpc64.sh
   compute-node-files/nodes
   compute-node-files/maui.sh
   compute-node-files/mom_priv-config
   compute-node-files/pbs_mom
   ```

   b. Copy the archive to the `/home/hpc` directory on each compute node. In the following example there are two compute nodes in the cluster, with the host names `compute_node1` and `compute_node2`:

   ```bash
   # scp compute-node-files.tar.gz compute_node1:/home/hpc
   # scp compute-node-files.tar.gz compute_node2:/home/hpc
   ```

**Results**

You are ready to extract and install the TORQUE packages on each compute node.
Related concepts:

Chapter 1, “Scope, requirements, and support,” on page 1

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.

Configuring TORQUE on the compute nodes

In order to use the Torque Resource Manager to control jobs in the cluster, you need to configure the Machine Oriented Mini-server on each compute node.

Before you begin

Complete the procedure described in “Preparing the TORQUE packages for the compute nodes” on page 20.

About this task

You need to follow these steps on each compute node.

The root user on the compute node performs this procedure.

Procedure

1. Extract the compute-node-files.tar.gz archive and install each TORQUE package as shown in the following example:

   # cd /home/hpc
   
   # tar zxf compute-node-files.tar.gz
   
   # cd compute-node-files/
   
   # ./torque-package-clients-linux-powerpc64.sh --install
   
   Installing TORQUE archive...
   
   Done.
   
   # ./torque-package-mom-linux-powerpc64.sh --install
   
   Installing TORQUE archive...
   
   Done.

2. Copy the Machine Oriented Mini-server files to the appropriate directories with the following commands:

   # cp /home/hpc/compute-node-files/mom_priv-config /var/spool/torque/mom_priv/config
   
   # cp /home/hpc/compute-node-files/pbs_mom /etc/init.d/

3. Prepare the pbs_mom service with the following commands:

   # chkconfig --add pbs_mom
   
   # chkconfig --level 3456 pbs_mom on
   
   # chkconfig --list pbs_mom

4. Start the pbs_mom service with the following command:

   # service pbs_mom start
Validating job submissions

Verify that TORQUE resource manager and Maui Cluster Scheduler are properly configured by submitting a basic test job and a multi-node test job.

Before you begin

Ensure that you have completed the following tasks:

- “Installing Maui cluster scheduler” on page 18
- “Installing Torque resource manager” on page 17
- “Preparing the TORQUE packages for the compute nodes” on page 20
- “Configuring TORQUE on the compute nodes” on page 22

About this task

The hpc user submits the test jobs on the cluster.

Note: The root user cannot submit the jobs on the cluster because of the TORQUE security controls.

The job basic job test and multi-node job test verify resource handling and job scheduling on your nodes.

Procedure

1. Verify that the Maui and TORQUE services are running with the following steps. Because the torque and maui software have been configured as services, the processes should automatically start after rebooting.
   a. On the management node, verify that the maui service and the pbs_server service are running. When these services are running, you can see output from the ps command similar to the output shown in the following example:

   ```
   # ps -ef | grep -E "pbs|maui"
   root 4091 1 0 11:16 ? 00:00:00 /usr/local/maui-3.3/sbin/maui
   root 4525 1 0 11:16 ? 00:00:00 /usr/local/sbin/pbs_server
   root 7253 7077 0 11:28 pts/1 00:00:00 grep -E pbs|maui
   ```
   b. On the compute nodes, verify that the pbs_mom service is running. When this service is running, you can see output from the ps command similar to the output shown in the following example:

   ```
   # ps -ef | grep pbs
   root 4467 1 0 11:16 ? 00:00:00 /usr/local/sbin/pbs_mom -p
   root 7144 7046 0 11:26 pts/1 00:00:00 grep pbs
   ```

2. Perform a basic job test on the management node with the following steps:
   a. Submit the job using the qsub command and view the status of the job using the qstat command as the hpc user on the management node, as shown in the following example:

   ```
   $ echo "sleep 30" | qsub
   1.mgmt_node.example.com
   $ qstat
   ```

   ```
   Job id  Name  User  Time Use $ Queue
   1.mgmt_node  STDIN  hpc  0 R batch
   ```
The output of the qstat command shows the following characteristics of the job:

**Job id**  The Job id field shows the ID associated with the job and the node where the job is running. The ID of the job running on the mgmt_node node in this example is 1.

**Name**  The Name field shows the name defined on the #PBS -N line in the PBS job file. If no job name is defined in the PBS job file, the default value of the Name field is the file name of the job. In this example, the job is from standard input, so the job name is STDIN.

**User**  The User field shows the name of the user that submitted the job.

**Time Use**  The Time Use field shows the amount of CPU time used by the job.

**S**  The S field shows the status of the job. In this example, the value of the S field is R, indicating that the job is running. When the job is complete, the value of the status field is C.

**Note:** If the value of the status column is Q (queued) when you run this test job, there is probably a configuration issue. If this occurs, review the installation and configuration steps to ensure they were completed correctly.

**Queue**  The Queue field shows the name of the queue that is handling the job. In this example, the job is the queue named batch.

3. To verify that the cluster is configured correctly, use the `mpirun` command to run the `hostname` command on each node to ensure that processes run successfully on each node. The parameters used in the following example with the `mpirun` command are:
   - The `-np` flag specifies the total number of copies of the process to run on the nodes.
   - The `-host` flag specifies the host names where the process will run.
   - The last parameter of the `mpirun` command is the command to run on the nodes.

   The following example shows how to use the `mpirun` command to run a simple process on all the nodes of your cluster.

   ```bash
   $ mpirun -np 2 --host compute_node1.example.com,compute_node2.example.com hostname
   compute_node1.example.com
   compute_node2.example.com
   ```

   If the `hostname` command runs successfully on each node, the host name of each node appears in the output of the `mpirun` command shown in this example. In this example, the output shows the host names of the two compute nodes in the test cluster, `compute_node1`, and `compute_node2`.

4. Perform a simple multi-node test using a PBS script with the following steps:
   a. On the management node, create a PBS script similar to the following example. Note the following in the example:
      - The lines beginning with the number sign (#) in the PBS script are TORQUE directives and are used to set TORQUE environment variables for the job.
      - In the following example, the file name of the PBS script is `multinode.pbs`.
      - In the following example, the host names of the compute nodes are `compute_node1` and `compute_node2`.
      - In the following example, the `-np` flag of the `mpirun` command is used to specify that two copies of the `hostname` command will run.

   ```bash
   #PBS -N node_test
   #PBS -q batch
   #PBS -l nodes=2,pmem=100m,walltime=00:30:00
   #PBS -M admin@example.com
   #PBS -m e
   #PBS -V
   
   mpirun -np 2 --host compute_node1,compute_node2 hostname
   ```
b. Submit the PBS script as the hpc user on the management node, and check the status of the job as shown in the following example:

```bash
$ qsub multinode.pbs
11.mgmt_node.example.com
[hpc@mgmt_node ~]$ qstat
Job id       Name  User     Time Use $ Queue
------------------------- ---------------- --------------- -------- - ----- 
1.mgmt_node   node_test   hpc  00:00:00 C batch
```

This example shows a job submission, the returned job number (1), and the qstat output which indicates whether the job is running or has already completed.

**Related concepts:**

Chapter 1, “Scope, requirements, and support,” on page 1

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.

### Installing additional advanced software

There are several advanced software packages you can use to enhance the capability of compute nodes for a POWER processor-based cluster. This discussion includes basic installation and configuration instructions for libhugetlbfs, the IBM Advance Toolchain for PowerLinux, the ATLAS math libraries, and the IBM XL C/C++ and IBM XL Fortran compilers

**Related concepts:**

Chapter 1, “Scope, requirements, and support,” on page 1

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.

### Installing libhugetlbfs

You can boost performance for some HPC workloads by using 16MB huge pages provided by the libhugetlbfs library.

**About this task**

You must install and configure all nodes (including the management node) because the libhugetlbfs environment variables are applied on the management node for jobs that run on the compute nodes.

The root user performs all the steps of this task.

**Procedure**

1. Download the newest libhugetlbfs library from the project home, at the following URL: [http://sourceforge.net/projects/libhugetlbfs/files/](http://sourceforge.net/projects/libhugetlbfs/files/)

2. Prepare and install the library. Note that libhugetlbfs build process will create both the 32-bit and the 64-bit versions on the Power architecture.
   a. Extract the archive file, as shown in the following example:
      ```bash
      # tar -C /usr/local/src -zxf libhugetlbfs-2.9.tar.gz
      ```
   b. Change to the top-level directory of the extracted source, as shown in the following example:
      ```bash
      # cd /usr/local/src/libhugetlbfs-2.9/
      ```
   c. Build and install the software package, as shown in the following example:
      ```bash
      # make
      # make install PREFIX=/usr/local
      ```
3. Create and mount the /libhugetlbfs file system.
4. Give the hpc user group privileges to use /libhugetlbfs.
   a. Create the libhuge group, as shown in the following example:
      ```bash
      # groupadd libhuge
      ```
   b. Make the hpc user a member of the libhuge group, as shown in the following example:
      ```bash
      # usermod -a -G libhuge hpc
      ```
   c. Give the libhuge group privileges to use the /libhugetlbfs directory and set the permissions as shown in the following example:
      ```bash
      # chgrp libhuge /libhugetlbfs
      # chmod 777 /libhugetlbfs
      ```
5. Reserve huge pages for compute jobs to use, by providing the number of desired pages in the
   nr_hugepages file. Clear any existing huge pages before you reserve a new number of huge pages, as
   shown in the following example:
   ```bash
   # echo 0 > /proc/sys/vm/nr_hugepages
   # echo 100 > /proc/sys/vm/nr_hugepages
   ```
6. Validate the configuration of libhugetlbfs.
   a. Verify that the permissions of the /libhugetlbfs file system are set correctly, as shown in the
      following example:
      ```bash
      # ls -ld /libhugetlbfs/
      drwxrwxrwx 2 root libhuge 0 Oct 8 20:40 /libhugetlbfs/
      ```
   b. Verify that the libhuge ld scripts are located in the directory where libhugetlbfs is installed, as
      shown in the following example:
      ```bash
      ls /usr/local/share/libhugetlbfs/
      ld ld.hugetlbfs ldscripts
      ```
   c. Verify that the correct number of huge pages is allocated by checking /proc/meminfo as shown in
      the following example:
      ```bash
      # cat /proc/meminfo | grep Huge
      ```
7. Make the settings for libhugetlbfs persistent by having the configuration occur when the node starts
   up.
   a. Edit the /etc/fstab file to include the following line:
      ```bash
      hugetlbfs /libhugetlbfs hugetlbfs mode=0777,gid=1000 0 0
      ```
      Note: The group ID for the libhuge group in this example is 1000. Verify the libhuge group ID by
      running the id command as the hpc user.
   b. Edit the /etc/sysctl.conf file to include the following parameters:
      ```bash
      vm.nr_hugepages=0
      vm.nr_hugepages=100
      ```
   c. Run the `sysctl -p` command to load settings from the default sysctl configuration file,
      `/etc/sysctl.conf`.

Results

When you have completed this process for each node, you can use 16MB huge pages on your cluster.
Related concepts:

Chapter 1, “Scope, requirements, and support,” on page 1

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.

Installing IBM Advance Toolchain for PowerLinux

The IBM Advance Toolchain for PowerLinux provides potential performance benefits by using newer open source compilers and runtime libraries than those that are provided in most Linux distributions.

About this task

If you determine that your applications will benefit from the IBM Advance Toolchain for PowerLinux, perform this process on each node of the cluster.

The root user performs the installation process.

The hpc user must perform some of the validation steps.

Procedure

1. Download the three IBM Advance Toolchain for PowerLinux 3.0 RPM packages for Red Hat Enterprise Linux from the following URL: http://linuxpatch.ncsa.uiuc.edu/toolchain/at/at3.0/redhat/RHEL5

   The following list shows the names of the specific files to download:
   • advance-toolchain-at3.0-runtime-3.0-0.ppc64.rpm
   • advance-toolchain-at3.0-devel-3.0-0.ppc64.rpm
   • advance-toolchain-at3.0-perf-3.0-0.ppc64.rpm

2. Install the RPM packages in the order shown in the following example:

   # rpm -i advance-toolchain-at3.0-runtime-3.0-0.ppc64.rpm
   # rpm -i advance-toolchain-at3.0-devel-3.0-0.ppc64.rpm
   # rpm -i advance-toolchain-at3.0-perf-3.0-0.ppc64.rpm

   The default installation location for the IBM Advance Toolchain for PowerLinux is the /opt/at3.0/ directory. The IBM Advance Toolchain for PowerLinux gcc compilers are installed in the /opt/at3.0/bin directory by default.

3. Run the createldhuge script to configure IBM Advance Toolchain for PowerLinux to work with libhugetlbfs, as shown in the following example:

   # /opt/at3.0/scripts/createldhuge.sh /usr/local/share/libhugetlbfs/ld.hugetlbfs /opt/at3.0/

4. Confirm the version of the gcc command installed by the Linux distribution is the gcc executable provided by the Linux distribution.

   # which gcc
   /usr/bin/gcc

5. Make the IBM Advance Toolchain for PowerLinux gcc available for the hpc user.

   a. Add the IBM Advance Toolchain for PowerLinux bin directory in the PATH environment variable for the hpc user so that the hpc user will use this version of the gcc command by default, as shown in the following example:

      # su - hpc
      $ export PATH=/opt/at3.0/bin:$PATH

   b. Verify that the IBM Advance Toolchain for PowerLinux version of gcc is now the default gcc command used by the hpc user, as shown in the following example:

      $ which gcc
      /opt/at3.0/bin/gcc
Results

If you complete this process on all the nodes, the cluster is configured to use the IBM Advance Toolchain for PowerLinux with libhugetlbfs.

Related concepts:

Chapter 1, “Scope, requirements, and support,” on page 1

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.

Installing the IBM XL C/C++ and Fortran compilers

Users who want the advantages of optimized compilers may benefit from the IBM XL compilers.

Before you begin

You can find more information about getting a license for these compilers at the following web sites:


Note: Users can also take advantage of the free 60-day trial for the IBM XL compilers. Here we provide instructions on how to download and install the trial versions.

You must ensure that the required compiler toolchain packages from the Linux distributor are installed on the system before you install the IBM XL compilers. You can do this with the `yum install` command as shown in the following example:

```
# yum install gcc gcc-c++ glibc.ppc glibc.ppc64 glibc-devel.ppc glibc-devel.ppc64 / 
libgcc.ppc libgcc.ppc64 libstdc++.ppc libstdc++.ppc64 libstdc++-devel.ppc 
libstdc++-devel.ppc64 perl
```

About this task

If you choose to use the XL C/C++ and XL Fortran compilers, perform this process on each node of the cluster.

The root user performs the installation process.

Procedure

1. Download the XL compiler trial versions from the following URLs:


   Note: You have to accept the license agreement for both compilers before you can go to the Download using http tab and click Download now to download the compiler archive files.

2. Install the XL C/C++ compiler.
   a. Prepare and install the XL C/C++ compiler from the directory where you extract the archive file, as shown in the following example. This process will install the compiler in the `/opt/ibmcmp/` directory by default:

      ```
      mkdir /usr/local/src/xlc
      # tar -C /usr/local/src/xlc -zxf xlc.11.1.0.0.1inux.eval.tar.gz
      # cd /usr/local/src/xlc/
      # ./xlc_install -rpmloc images/rpms/
      ```
The following example output shows the portions of the xlc_install command output that you need to interact with the installation process. The places where output was omitted from this example are indicated by the three periods ("..."):

Press Enter to continue viewing the license agreement, or, Enter "1" to accept the agreement, "2" to decline it or "99" to go back to the previous screen, "3" Print, "4" Read non-IBM terms.

1

... Link Source
=================== ====================
/usr/bin/gxlc /opt/ibmcmp/vacpp/11.1/bin/gxlc
/usr/bin/gxlc++ /opt/ibmcmp/vacpp/11.1/bin/gxlc++
/usr/bin/gxlC /opt/ibmcmp/vacpp/11.1/bin/gxlC
/usr/bin/xlc /opt/ibmcmp/vacpp/11.1/bin/xlc
/usr/bin/xlc++ /opt/ibmcmp/vacpp/11.1/bin/xlc++
/usr/bin/xlC /opt/ibmcmp/vacpp/11.1/bin/xlC
/usr/bin/xlc_r /opt/ibmcmp/vacpp/11.1/bin/xlc_r
/usr/bin/xlC_r /opt/ibmcmp/vacpp/11.1/bin/xlC_r
/usr/bin/xlc++_r /opt/ibmcmp/vacpp/11.1/bin/xlc++_r
/usr/bin/xlC_r /opt/ibmcmp/vacpp/11.1/bin/xlC_r

Do you want to proceed with the symbolic links?
Please type "yes" or "no": yes

Installation Completed.
Filename of the installation log: /opt/ibmcmp/vacpp/11.1/xlc_install.log

b. Run the xlc command to verify that you see the compiler information page, as shown in the following example:

```
# xlc
xlc(1) IBM XL C/C++ for Linux, V11.1 xlc(1)
```

NAME

xlc, xlc++, xlC, cc, c89, c99 and related commands - invoke the IBM XL C/C++ compiler.

SYNTAX

```
<invocation-command> [ <option> | <inputfile> ]
```

... 3. Install the XL Fortran compiler.

a. Prepare and install the XL Fortran compiler from the directory where you extract the archive file, as shown in the following example. This process will install the compiler in the /opt/ibmcmp/ directory by default:

```
# mkdir /usr/local/src/xlf
# tar -C /usr/local/src/xlf -zxf xlf.13.1.0.0.linux.eval.tar.gz
# cd /usr/local/src/xlf/
# ./xlf_install -rpmloc images/rpms/
```

The following example output shows the portions of the xlf_install command output which you need to interact with the installation process. The places where output was omitted from this example are indicated by the three periods ("..."):

Type "yes" even if you have "IBM XL SMP Version 2.1.0.0-100630 for Linux", "IBM XL MASS Version 6.1.0.0-100630 for Linux" already installed at the default installation path.

Do you want to proceed with the installation?
Please type "yes" or "no": yes

...
"3" Print, "4" Read non-IBM terms.

1
...
Do you want to proceed with the symbolic links?
  Please type "yes" or "no": yes
...
Installation Completed.
Filename of the installation log: /opt/ibmcmp/xlf/13.1/xlf_install.log

b. Run the xlf command to verify that you see the compiler information page, as shown in the following example:

```
# xlf
xlf(1) IBM XL Fortran for Linux, V13.1 xlf(1)

NAME
  xlf, xlf_r, f77, fort77, xlf90, xlf90_r, f90, xlf95, xlf95_r, f95,
  xlf2003, xlf2003_r, f2003 - invoke the IBM XL Fortran compiler.

SYNTAX
  <invocation-command> [ <option> | <inputfile> ]
```

Results

If you complete this process on all the nodes of your cluster, the XL C/C++ and XL Fortran compilers are installed and ready to use.

Related concepts:

Chapter 1, “Scope, requirements, and support,” on page 1

In this blueprint, you can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.

Installing ATLAS math libraries

Automatically Tuned Linear Algebra Software (ATLAS) is a math library that can be used to compile workloads such as Linpack and HPC Challenge.

Before you begin

Download the newest stable version of ATLAS, which is 3.8.3 at the time this paper was written:


Note: At the time this document was written, the newest stable version was ATLAS 3.8.3, which is used in the examples in this document.

About this task

The build process takes several hours to complete, so you may prefer to compile the software on one node and copy the compiled versions to your other nodes with the identical processor architecture.

The root user performs all the steps of this process.

Procedure

1. Extract the ATLAS tar archive file, as shown in the following example:

```
# tar -jxf atlas3.8.3.tar.bz2 -C /usr/local/
```

2. Configure the ATLAS setup.

As root, go into the top level ATLAS directory and create a build directory where you will run the configure and make commands, as shown in the following example:
# cd /usr/local/ATLAS/
# mkdir obj64
# cd obj64/
# ../configure -b 64

- The example uses a directory called obj64 as the 64-bit library build location.
- The -b 64 option tells the ATLAS configure command to build the 64-bit libraries.

3. Run the make step to build, test, and optimize the library.

   Note: This step may take several hours to complete. The ATLAS math libraries employ a self-tuning automated optimization process of building, running, assessing the results, and using the best options. The following example shows the invocation of the make command, and modified output with the last several lines of message produced by the make command. The omitted lines of output are represented by a line containing three periods ("...") in the example output.

   # make

   ...  
   ATLAS install complete. Examine ATLAS/bin/arch/INSTALL_LOG/SUMMARY.LOG for details.
   make[1]: Leaving directory `/usr/local/ATLAS/obj64'
   make clean
   make[1]: Entering directory `/usr/local/ATLAS/obj64'
   rm -f *.o.x* config?.out *core*
   make[1]: Leaving directory `/usr/local/ATLAS/obj64'

4. After the make command completes, run the make check command to check the libraries. This command produces a report showing a list of tests that either pass or fail. Ensure that all of the tests pass.

5. Install the libraries. The following example shows a listing of the libraries that the make install command installs in the /usr/local/ATLAS/obj64/lib/ directory:

   # make install
   # ls lib/
   libatlas.a libf77blas.a libptcblas.a libtstatlas.a Make.inc
   libcblas.a liblapack.a libptf77blas.a Makefile

Results

After you install the ATLAS libraries on the nodes of the cluster, the libraries are ready to use.

Example

The order you use to link to the ATLAS libraries can affect how they function. The ATLAS FAQs provide more information about this subject. The following example shows a correct order to link the libraries:

   -lc -L/usr/local/ATLAS/obj64/lib/ -llapack -lptcblas -lptf77blas -latlas

Related concepts:

Chapter 1, “Scope, requirements, and support,” on page 1

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.

Building specialized versions of Open MPI

You can configure Open MPI to integrate better and make better use of other components in an HPC software stack.

Open MPI is highly configurable both at build time and at run time. Although Open MPI will function well on POWER-based systems as installed from the IBM Installation Toolkit, you can optimize Open MPI to work better with other software that is installed on the HPC cluster. This topic discusses methods
to configure Open MPI to work better with various software components that are discussed in this blueprint. Specifically, this discussion covers integrating the following packages with Open MPI:

- TORQUE resource manager
- IBM Advance Toolchain for PowerLinux
- IBM XL C/C++ and Fortran compilers
- libhugetlbfs

Related concepts:

Chapter 1, “Scope, requirements, and support,” on page 1

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.

**Building Open MPI with TORQUE**

Configuring Open MPI to work directly with the TORQUE resource manager can simplify launching and managing MPI jobs across a set of resources.

**Before you begin**

Ensure that the TORQUE resource manager is installed on the nodes in your cluster, as described in Chapter 4, “Installing the Management Node,” on page 17.

**About this task**

The `hpc` user performs most of the steps in this task.

The root user performs the build and installation processes in this task.

This process can be used to install any new versions of Open MPI.

The process shows how to build and make the package on the management node. You can then create a tar archive file of the `/usr/local/openmpi` library and then copy the archive file to each compute node and then extract the files. After these steps, you must change the PATH and LD_LIBRARY settings in the `.bashrc` file to use the new library.

**Procedure**

1. On the management node, download the latest Open MPI source tar file in the 1.4.x release series from the following location: [http://www.open-mpi.org/software/ompi/v1.4/](http://www.open-mpi.org/software/ompi/v1.4/)

   **Note:** This example uses Open MPI version 1.4.2, which is the latest stable release of Open MPI at the time of this writing.

2. As the root user on the management node, extract the sources and go to the source directory, as shown in the following example:

   ```bash
   # tar xjf openmpi-1.4.2.tar.bz2 -C /usr/local/src
   # cd /usr/local/src/openmpi-1.4.2
   ```

3. On the management node, configure and build a Torque-knowledgeable version of Open MPI. Do this by using the `--with-tm` flag for the configure script. Specifically, set the value of the `--with-tm` flag to the directory location where Open MPI can reference `include/tm.h`. If you have followed the instructions in this blueprint so far, the directory to use is `/usr/local/torque-2.4.8/src` as shown in the following example. After the configure step, run the `make` command and the `make install` command.

   ```bash
   ./configure --prefix=/usr/local/openmpi-1.4.2-tm \
   --with-platform=contrib/platform/ibm/optimized-ppc64-gcc --with-tm=/usr/local/torque-2.4.8/src
   # make
   # make install
   ```
4. On the management node, update the relevant environment variables of the hpc user to enable use of the TORQUE resource manager-aware version of Open MPI as shown in the following example:

```bash
# su - hpc
$ export PATH=/usr/local/openmpi-1.4.2-tm/bin:$PATH
$ export LD_LIBRARY_PATH=/usr/local/openmpi-1.4.2-tm/lib:$LD_LIBRARY_PATH
```

**Note:** You may also remove the previous version of Open MPI from PATH and LD_LIBRARY_PATH. However the syntax in this example sets the updated library to be found first in the path, so any older library in the path has no effect.

You can use the following example to make these updates to the .bashrc file:

```bash
$ cat >> /home/hpc/.bashrc <<EOF
export PATH=/usr/local/openmpi-1.4.2-tm/bin:$PATH
export LD_LIBRARY_PATH=/usr/local/openmpi-1.4.2-tm/lib:$LD_LIBRARY_PATH
EOF
```

5. On the management node, run `ompi_info` and use the `grep` command to retrieve the lines containing "plm" to ensure that the new build of Open MPI has TORQUE integration. If the TORQUE manager component built correctly, you will see the `tm` entry listed as a component of the `plm` (Process Launch Module) framework, as shown in the following example:

```bash
$ ompi_info | egrep plm:
MCA plm: rsh (MCA v2.0, API v2.0, Component v1.4.2)
MCA plm: slurm (MCA v2.0, API v2.0, Component v1.4.2)
MCA plm: tm (MCA v2.0, API v2.0, Component v1.4.2)
```

6. On the management node, as the root user, prepare the tar archive file of the openmpi-1.4.2-tm directory contains the updated Open MPI library, and distributed the archive to all of the compute nodes, as shown in the following example:

```bash
# cd /usr/local
# tar cvf openmpi-1.4.2-tm.tar openmpi-1.4.2-tm
# scp openmpi-1.4.2-tm.tar compute_node1:/usr/local/
# scp openmpi-1.4.2-tm.tar compute_node2:/usr/local/
```

**Note:** In this example, the compute nodes are named compute_node1 and compute_node2.

7. On each of the compute nodes, install the TORQUE resource manager-aware version of Open MPI, and set up the environment for the hpc user.

   a. As the root user on each compute node, extract the tar archive, as shown in the following example

```bash
# cd /usr/local
# tar xvf openmpi-1.4.2-tm.tar
```

   b. As the hpc user on each compute node, configure the appropriate environment variables, as shown in the following example:

```bash
$ export PATH=/usr/local/openmpi-1.4.2-tm/bin:$PATH
$ export LD_LIBRARY_PATH=/usr/local/openmpi-1.4.2-tm/lib:$LD_LIBRARY_PATH
```

   You can use the following example to make these updates to the .bashrc file:

```bash
$ cat >> /home/hpc/.bashrc <<EOF
export PATH=/usr/local/openmpi-1.4.2-tm/bin:$PATH
export LD_LIBRARY_PATH=/usr/local/openmpi-1.4.2-tm/lib:$LD_LIBRARY_PATH
EOF
```

   c. On each compute node, run `ompi_info` and use the `grep` command to retrieve the lines containing "plm" to ensure that the new build of Open MPI has TORQUE integration as shown in the following example:

```bash
$ ompi_info | egrep plm:
MCA plm: rsh (MCA v2.0, API v2.0, Component v1.4.2)
MCA plm: slurm (MCA v2.0, API v2.0, Component v1.4.2)
MCA plm: tm (MCA v2.0, API v2.0, Component v1.4.2)
```
Configuring Open MPI for use with IBM Advance Toolchain for PowerLinux

You can configure Open MPI for use with IBM Advance Toolchain for PowerLinux with a single command string.

Before you begin

Ensure that the Open MPI and the IBM Advance Toolchain for PowerLinux RPMs are installed on the system.

About this task

The following procedure should be completed on all nodes.

Procedure

1. Adjust the PATH environment variable so that the Advance Toolchain installation bin directory is at the head of the PATH list, as shown in the following example:

   ```
   $ export PATH=/opt/at3.0/bin:$PATH
   ```

   Once this is done, all builds done with the Open MPI wrapper compilers (such as mpicc, mpi90, and so on), regardless of which Open MPI build you are using, will use the compilers and runtime environment provided by the IBM Advance Toolchain for PowerLinux.

2. Validate the use of IBM Advance Toolchain for PowerLinux with the following steps:
   a. Run the `which gcc` command and ensure that the `gcc` used is coming from the `/opt/at3.0/bin` directory, as shown in the following example:

      ```
      $ which gcc
      /opt/at3.0/bin/gcc
      ```

   b. Build an MPI program using the mpicc compiler wrapper (now using IBM Advance Toolchain for PowerLinux) and run the `ldd` command on the resulting executable. Make sure that the `libc.so.6` library (and other libraries) resolve to libraries in the `/opt/at3.0/lib64` directory hierarchy:

      ```
      $ mpicc -o hello_c hello_c.c
      $ ldd hello_c
      ```

      ```
      ldd hello_c
      linux-vdso64.so.1 => (0x0000000000100000)
      libmpl.so.0 => /usr/local/openmpi-1.4.2-tm/lib/libmpl.so.0 (0x0000000000120000)
      libopen-rte.so.0 => /usr/local/openmpi-1.4.2-tm/lib/libopen-rte.so.0 (0x0000000000140000)
      libopen-pal.so.0 => /usr/local/openmpi-1.4.2-tm/lib/libopen-pal.so.0 (0x0000000000160000)
      libdl.so.2 => /opt/at3.0/lib64/power6/libdl.so.2 (0x0000000000180000)
      libnsl.so.1 => /opt/at3.0/lib64/power6/libnsl.so.1 (0x00000000001a0000)
      libutil.so.1 => /opt/at3.0/lib64/power6/libutil.so.1 (0x00000000001c0000)
      libm.so.6 => /opt/at3.0/lib64/power6/libm.so.6 (0x00000000001e0000)
      libpthread.so.0 => /opt/at3.0/lib64/power6/libpthread.so.0 (0x0000000000200000)
      libc.so.6 => /opt/at3.0/lib64/power6/libc.so.6 (0x0000000000220000)
      /opt/at3.0/lib64/ld64.so.1 (0x0000000000240000)
      ```

   ```
   Note:
   ```

   ```
   $$ mpicc -o hello_c hello_c.c
   $ ldd hello_c
   ```

   ```
   ldd hello_c
   linux-vdso64.so.1 => (0x0000000000100000)
   libmpl.so.0 => /usr/local/openmpi-1.4.2-tm/lib/libmpl.so.0 (0x0000000000120000)
   libopen-rte.so.0 => /usr/local/openmpi-1.4.2-tm/lib/libopen-rte.so.0 (0x0000000000140000)
   libopen-pal.so.0 => /usr/local/openmpi-1.4.2-tm/lib/libopen-pal.so.0 (0x0000000000160000)
   libdl.so.2 => /opt/at3.0/lib64/power6/libdl.so.2 (0x0000000000180000)
   libnsl.so.1 => /opt/at3.0/lib64/power6/libnsl.so.1 (0x00000000001a0000)
   libutil.so.1 => /opt/at3.0/lib64/power6/libutil.so.1 (0x00000000001c0000)
   libm.so.6 => /opt/at3.0/lib64/power6/libm.so.6 (0x00000000001e0000)
   libpthread.so.0 => /opt/at3.0/lib64/power6/libpthread.so.0 (0x0000000000200000)
   libc.so.6 => /opt/at3.0/lib64/power6/libc.so.6 (0x0000000000220000)
   /opt/at3.0/lib64/ld64.so.1 (0x0000000000240000)
   ```

   Related concepts:

   Chapter 1, “Scope, requirements, and support,” on page 1

   This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.

Configuring Open MPI for use with IBM XL compilers

Put your short description here; used for first paragraph and abstract.
Before you begin

Ensure that Open MPI and the IBM XL Compiler RPMs are installed on the system.

About this task

This procedure will enable the use of Open MPI to build and run HPC applications with the IBM XL compilers. The use of the XL compilers can provide significant performance improvements over the distro-supplied compilers.

This procedure does not require that Open MPI be reconfigured or rebuilt. It relies solely on enhancing the Open MPI implementation to be knowledgeable of the XL compilers, therefore it can be done for either Open MPI build (the rpm installed version or the version integrated with torque).

The procedure given below is specifically for the xlc compiler. However, the same procedure can be followed to enable all of the languages and variants supported by the XL compilers to be used with Open MPI.

On all nodes, as the root user, follow the procedures below.

Procedure

1. To create a wrapper compiler to integrate the use of xlc with Open MPI, complete the following steps:
   a. Run the following command:
      
      ```
      # ompi_install_dir=/usr/local/openmpi-1.4.2-tm/
      ```
   b. In the Open MPI binary directory, symbolically link opal_wrapper to the desired wrapper compiler name (in this case, mpixlc):
      
      ```
      # ln -s ${ompi_install_dir}/bin/opal_wrapper ${ompi_install_dir}/bin/mpixlc
      ```
   c. In the Open MPI share/openmpi directory, copy the mpicc-wrapper-data.txt file to the mpixlc-wrapper-data.txt file:
      
      ```
      # cd ${ompi_install_dir}/share/openmpi
      # cp mpicc-wrapper-data.txt mpixlc-wrapper-data.txt
      ```
   d. Edit the mpixlc-wrapper.txt file as shown in the following example:
      
      ```
      # diff mpicc-wrapper-data.txt mpixlc-wrapper-data.txt
      14c14
      < compiler=gcc
      ---
      > compiler=xlc
      17,18c17,18
      < compiler_flags=-pthread -m64
      < linker_flags= -m64
      ---
      > compiler_flags=-qthreaded -q64
      > linker_flags= -q64
      ```
      Once this is done, you should be able to build your applications with mpixlc and it will use the IBM xlc compiler.

2. To create a wrapper compiler to integrate the use of xlf with Open MPI, complete the following steps:
   a. Run the following command:
      
      ```
      # ompi_install_dir=/usr/local/openmpi-1.4.2-tm/
      ```
   b. In the Open MPI binary directory, symbolically link opal_wrapper to the desired wrapper compiler name (in this case, mpixlf):
      
      ```
      # ln -s ${ompi_install_dir}/bin/opal_wrapper ${ompi_install_dir}/bin/mpixlf
      ```
   c. In the Open MPI share/openmpi directory, copy the mpif77-wrapper-data.txt file to the mpixlf-wrapper-data.txt file.
# cd ${ompi_install_dir}/share/openmpi
# cp mpif77-wrapper-data.txt mpixlf-wrapper-data.txt

d. Edit the mpixlf-wrapper.txt file as shown in the following example:

```diff
  14c14
  < compiler=gfortran
  ---
  > compiler=xlf
  17,18c17,18
  < compiler_flags=-pthread -m64
  < linker_flags= -m64
  ---
  > compiler_flags=-qthreaded -q64
  > linker_flags= -q64
```

Once this is done, you should be able to build your applications with mpixlf and it will use the IBM XLF compiler.

3. To verify the compiler options that are being used, run the compiler with the --showme option (this step can be done as hpc user):

```
$ mpixlc --showme
xlc -I/usr/local/openmpi-1.4.2/include -qthreaded -q64 -q64 -L/usr/local/openmpi-1.4.2/lib -lmpi -lopenrte -lopen-pal -ldl -Wl,-export-dynamic -lnsl -lutil -lm -ldl

$ mpixlf --showme
xlf -I/opt/openmpi/1.4.2/include -qthreaded -q64 -q64 -L/opt/openmpi/1.4.2/lib -lmpi_f77 -lmpi -lopen-rte -lopen-pal -ldl -Wl,-export-dynamic -lnsl -lutil -lm -ldl
```

### Results

If -I/usr/local/${ompi_install_dir}/include and -L/usr/local/${ompi_install_dir}/lib are shown in the output, then you have successfully configured Open MPI to build and run HPC application with IBM XL compilers. Note that the other wrapper compilers for mpif77, mpif90, mpic++, and the _r variants can be handled similarly.

### Related concepts:

- Chapter 1, “Scope, requirements, and support,” on page 1

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.

### Using Open MPI with huge pages

If you have libhugetlbfs installed, you can choose to use 16MB huge pages with Open MPI when you start a distributed program.

#### Before you begin

Ensure that Open MPI is installed and that libhugetlbfs is installed.

#### About this task

The standard Open MPI configuration includes support for optimal use of RDMA-based communications, such as InfiniBand. This requires the use of special memory management routines within the Open MPI library to manage pages used in RDMA transfers. However, this is incompatible with the use of an interposer memory management library, such as libhugetlbfs.

To enable use of libhugetlbfs with Open MPI, the IBM Installation Toolkit contains a version of Open MPI which does not use the embedded Open MPI memory manager. After Open MPI is installed from the IBM Installation Toolkit, and you have your environment setup to use it, you can use libhugetlbfs as an
interposer library with the LD_PRELOAD mechanism. This enables existing software to take advantage of libhugetlbfs without recompiling or relinking.

**Procedure**

1. To make use of 16MB huge pages, start the distributed application with the environment variable LD_PRELOAD set to libhugetlbfs.so and HUGETLB_MORECORE set to yes. The following example shows how the hpc user can start an application with these settings:

   ```bash
   $ mpirun -x LD_PRELOAD=libhugetlbfs.so -x HUGETLB_MORECORE=yes \
   -x OMP_MCA_memory_ptmalloc2_disable=1 -np <#> <program>
   ``

   **Note:** In this example, the `-x` flag of the `mpirun` command tells `mpirun` to propagate the designated environment setting to all of the processes of the distributed job.

2. Verify that huge pages are used by the application.

   You can verify the use of libhugetlbfs by running a job which does dynamic memory allocation and then observing the values of HugePages_Total and HugePages_Free in `/proc/meminfo`. If the job uses huge pages, when the application runs, the value of HugePages_Free decreases from the value it shows before you run the program.

   a. Check the values of HugePages_Total and HugePages_Free before you run the program, as shown in the following example:

      ```bash
      # egrep 'HugePages_(Total|Free)' /proc/meminfo
      HugePages_Total:   400
      HugePages_Free:    400
      ```

   b. Check the values of HugePages_Total and HugePages_Free while the program is running, as shown in the following example:

      ```bash
      # egrep 'HugePages_(Total|Free)' /proc/meminfo
      HugePages_Total:   400
      HugePages_Free:    80
      ```

3. Check the values of HugePages_Total and HugePages_Free when the program is has completed, as shown in the following example:

   ```bash
   # egrep 'HugePages_(Total|Free)' /proc/meminfo
   HugePages_Total:   400
   HugePages_Free:    400
   ```

**Related concepts:**

[Chapter 1, “Scope, requirements, and support,” on page 1]

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.

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**Testing the InfiniBand interconnect performance with Intel MPI Benchmark**

Validate the InfiniBand interconnect using a commonly used benchmark called Intel MPI Benchmark (IMB).

This section focuses on verifying the performance of the InfiniBand interconnects. This is an important step in verifying the performance of your cluster because if the interconnects cannot perform well, they can become a bottleneck for multi-node runs. You can complete the steps in each of the following sections as the hpc user.
Building IMB

IMB can be run on a single node, but for the purposes of testing InfiniBand performance, you will want to use at least two nodes for the test so that the messages will be passed across the InfiniBand link and not just within the shared memory of a single system.

About this task

Perform the following procedure on all of the nodes.

Procedure

1. Download IMB-3.2 from the following link: http://software.intel.com/en-us/articles/intel-mpi-benchmarks/
2. Untar the package and change directory into the /src directory with the following commands:
   
   ```
   tar zxvf IMB_3.2.tgz -C /home/hpc
cd /home/hpc/imb/src/
   ```
3. Edit the make_ict makefile to change the assignment of the CC value from mpiic to mpicc as shown:
   
   ```
   LIB_PATH =
   LIBS =
   CC = mpicc
   ifeq (,$(shell which ${CC}))
   $(error ${CC} is not defined through the PATH <clipped> )
   endif
   OPTFLAGS =
   CLINKER = ${CC}
   LDFLAGS =
   CPPFLAGS =
   export CC LIB_PATH LIBS OPTFLAGS CLINKER LDFLAGS CPPFLAGS
   include Makefile.base
   ```
4. Run the make command. When the make command completes, the IMB-MPI1 executable is shown with other object files and executables.

Running IMB

You can run IMB to determine whether you need to affinitize the processes to increase performance.

Procedure

1. Run IMB_MPI1 pingpong from management node:
   
   ```
   $ cd /home/hpc
   $ mpirun -np 2 -host compute_node1,compute_node2 imb/src/IMB-MPI1 pingpong
   ```
   Verify that you see the IMB output on your screen.
2. Run IMB in a pbs job with the following steps. This example job runs three IMB-MPI1 workloads: pingpong, sendrecv, and exchange across two nodes.
Note: Perform this step for every InfiniBand link.

a. Create the job.pbs file as shown:

```bash
#PBS -N imb_2node
#PBS -q batch
#PBS -l nodes=2,pmem=100m,walltime=00:30:00
#PBS -M admin@example.com
#PBS -m e
#PBS -V

cd /home/hpc

mpirun -np 2 --host compute_node1,compute_node2 imb/src/IBM-MPI1 pingpong
```

3. Submit the job with the `qsub` command, as shown in the following example:

```
$ qsub job.pbs
3.mgmt_node.example.com
```

Results

Two new output files are available after running the job: one containing job outputs and another containing any errors. They are named `<job name>.o<job identifier>` and `<job name>.e<job identifier>`, respectively. These output files are located on the compute node where the job ran.

The following output is the `imb_2node.o3` file for the job that ran in the test environment, including the output of expected performance for the pingpong, sendrecv, and exchange workloads on a single InfiniBand link:

```
#---------------------------------------------------
# Intel (R) MPI Benchmark Suite V3.2, MPI-1 part
#---------------------------------------------------
# Machine : ppc64
# System : Linux
# Release : 2.6.32.12-0.7-ppc64
# Version : #1 SMP 2010-05-20 11:14:20 +0200
# MPI Version : 2.1
# MPI Thread Environment: MPI_THREAD_SINGLE

# New default behavior from Version 3.2 on:
# the number of iterations per message size is cut down
# dynamically when a certain run time (per message size sample)
# is expected to be exceeded. Time limit is defined by variable
# "SECS_PER_SAMPLE" (=> IMB_settings.h)
# or through the flag => -time

# Calling sequence was:
# IMB-MPI1 pingpong sendrecv exchange

# Minimum message length in bytes: 0
# Maximum message length in bytes: 4194304
#
# MPI_Datatype : MPI_BYTE
# MPI_Datatype for reductions : MPI_FLOAT
# MPI_Op : MPI_SUM
#
# List of Benchmarks to run:
# PingPong
```
# Sendrecv
# Exchange
#Benchmarking PingPong
# #processes = 2
#---------------------------------------------------

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#---------------------------------------------------

# Benchmarking Sendrecv
# #processes = 2
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# Benchmarking Exchange
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82  Blueprints: Setting up an HPC cluster with Red Hat Enterprise Linux
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# All processes entering MPI_Finalize

Related concepts:

Chapter 1, “Scope, requirements, and support,” on page 1

This blueprint applies to PowerLinux (POWER6 and later). You can learn more about this blueprint, including the intended audience, the scope and purpose, the hardware and software requirements for the tasks detailed in this blueprint, and the types of support available to you.

Related information

You can find additional information about the processes and tools described in these procedures.

IBM Installation
Toolkit for PowerLinux

Open MPI

IBM Advance
Toolchain for PowerLinux
[ftp://linuxpatch.ncsa.uiuc.edu/toolchain](ftp://linuxpatch.ncsa.uiuc.edu/toolchain)

TORQUE Resource Manager

Maui Cluster Scheduler

IBM XL C/C++ and XL Fortran Compilers
libhugetlbfs
http://sourceforge.net/projects/libhugetlbfs/

ATLAS math libraries
http://sourceforge.net/projects/math-atlas/

Related concepts:
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IBM Installation
Toolkit for PowerLinux

Open MPI
http://www.open-mpi.org/

IBM Advance
Toolchain for PowerLinux
ftp://linuxpatch.ncsa.uiuc.edu/toolchain

TORQUE Resource Manager
http://www.clusterresources.com/torquedocs21/

Maui Cluster Scheduler

IBM XL C/C++ and XL Fortran Compilers

libhugetlbfs
http://sourceforge.net/projects/libhugetlbfs/

ATLAS math libraries
http://sourceforge.net/projects/math-atlas/

Related concepts:
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